

HARDI, QBI and ODF Reconstruction

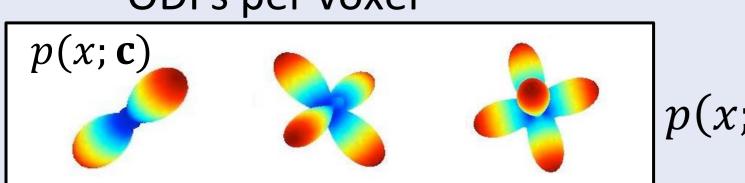
- High Angular Resolution Diffusion Imaging (HARDI) can be used to study the neuronal fiber architecture of the brain in order to study causes of neurological diseases.
- Current *Q-Ball Imaging* (QBI) methods [1,2,3] estimate the Orientation Distribution Function (ODF) p(x), $x \in S^2$, using a Spherical Harmonics (SH) basis representation for the HARDI signal $s(x), x \in S^2$.

HARDI Signal $s(x_i), x_i \in S^2, i = 1, ..., n$

 $\mathbf{c}_{LS} = \operatorname{argmin}_{c \in \mathbb{R}^L}$

 $s(x_i) = \sum_{i=1}^{n}$

ODFs per voxel



 $p(x; \mathbf{c}) = \frac{1}{4\pi} + \frac{1}{16\pi^2}$ • However, due to signal noise, ODF estimates may contain negative values, which are physically impossible and thus incorrect.

Paper Contributions

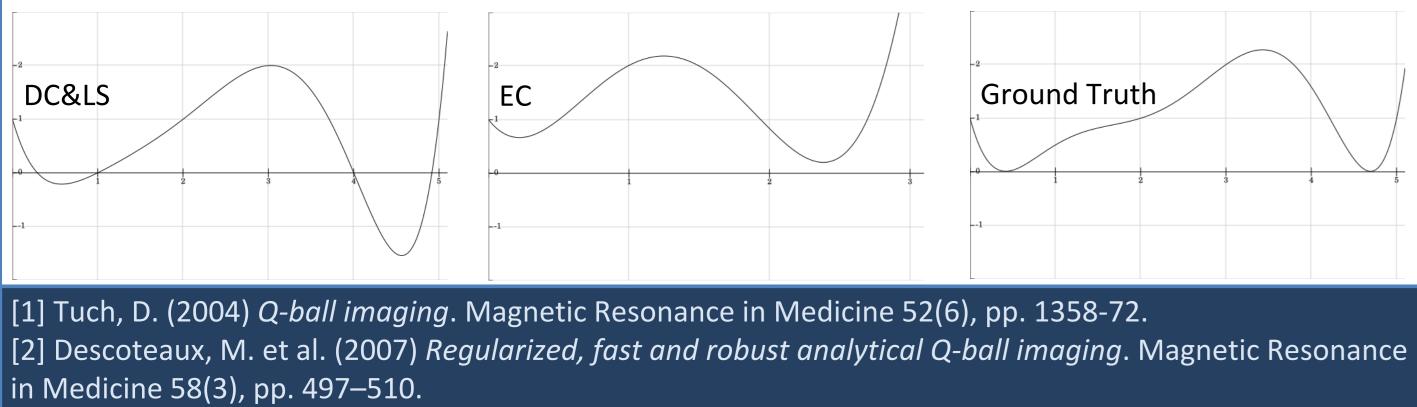
• We propose two methods for estimating nonnegative ODFs from HARDI data.

 $\mathbf{c}_{\infty} = \operatorname{argmin}_{\mathbf{c} \in \mathbf{R}^{L}} \| \mathbf{B}\mathbf{c} - \mathbf{s} \|_{2}$ s.t. $p(x, \mathbf{c}) \ge 0 \ \forall x \in S^{2}$

• The fundamental challenge is that there are infinitely many constraints.

State of the Art

- The discretely constrained (DC) method [4] enforces nonnegativity on a finite grid, which does not guarantee nonnegativity everywhere.
- The eigenvalue constrained (EC) method [5] guarantees nonnegativity, but does not solve P_{∞} , which can result in a distorted estimate of the ODF.



[3] Aganj, I. et al. (2010). Reconstruction of the orientation distribution function in single- and multiple-shell *q-ball imaging within constant solid angle*. Magnetic Resonance in Medicine 64(2), pp. 554–566. [4] Goh, A. et al. (2009). Estimating orientation distribution functions with probability density constraints and spatial regularity. MICCAI, 12(1), pp. 877–885.

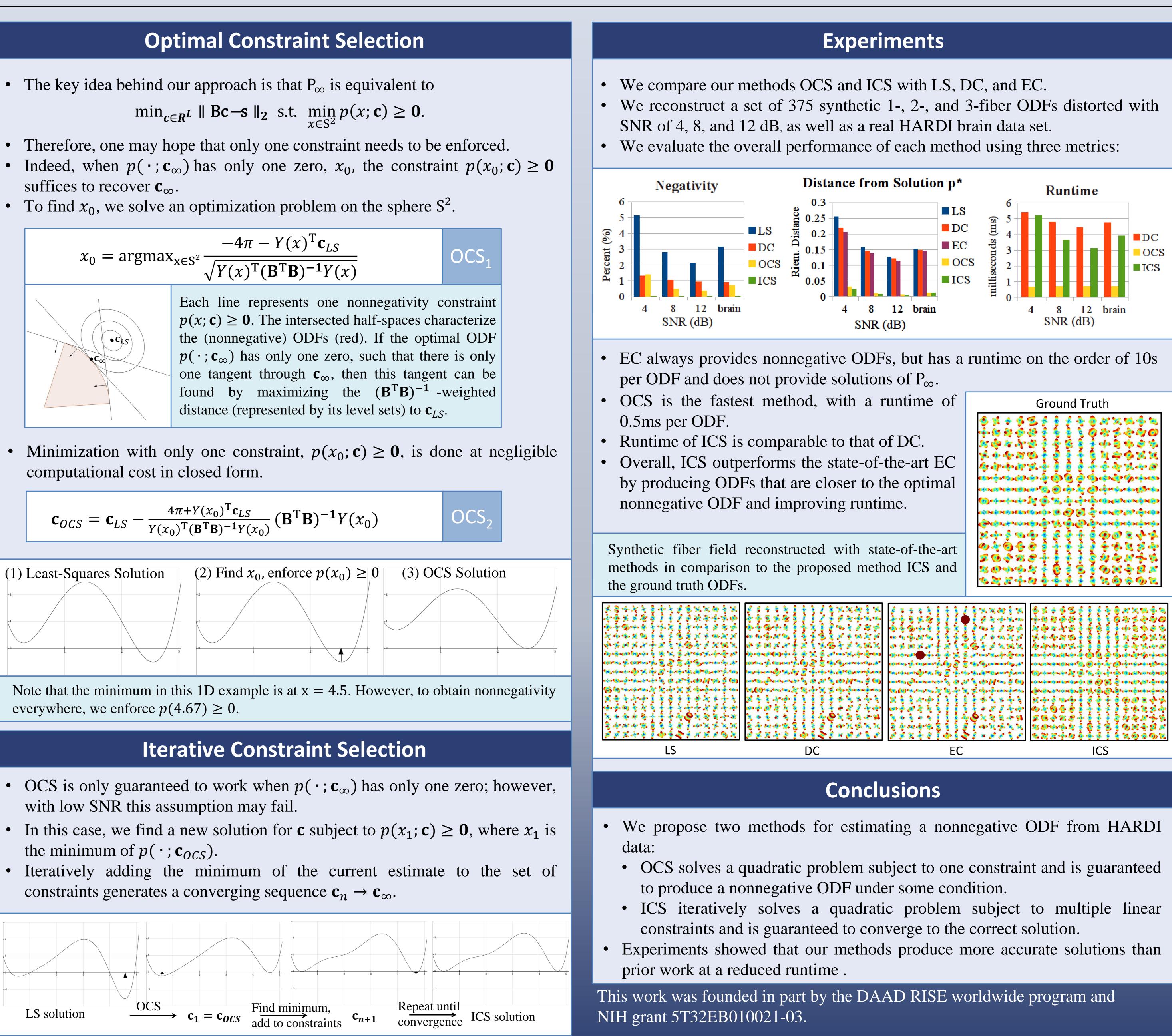
[5] Schwab, E. et al. (2012) Estimation of non-negative ODFs using the eigenvalue distribution of spherical functions, MICCAI, 15(2), pp. 322-330.

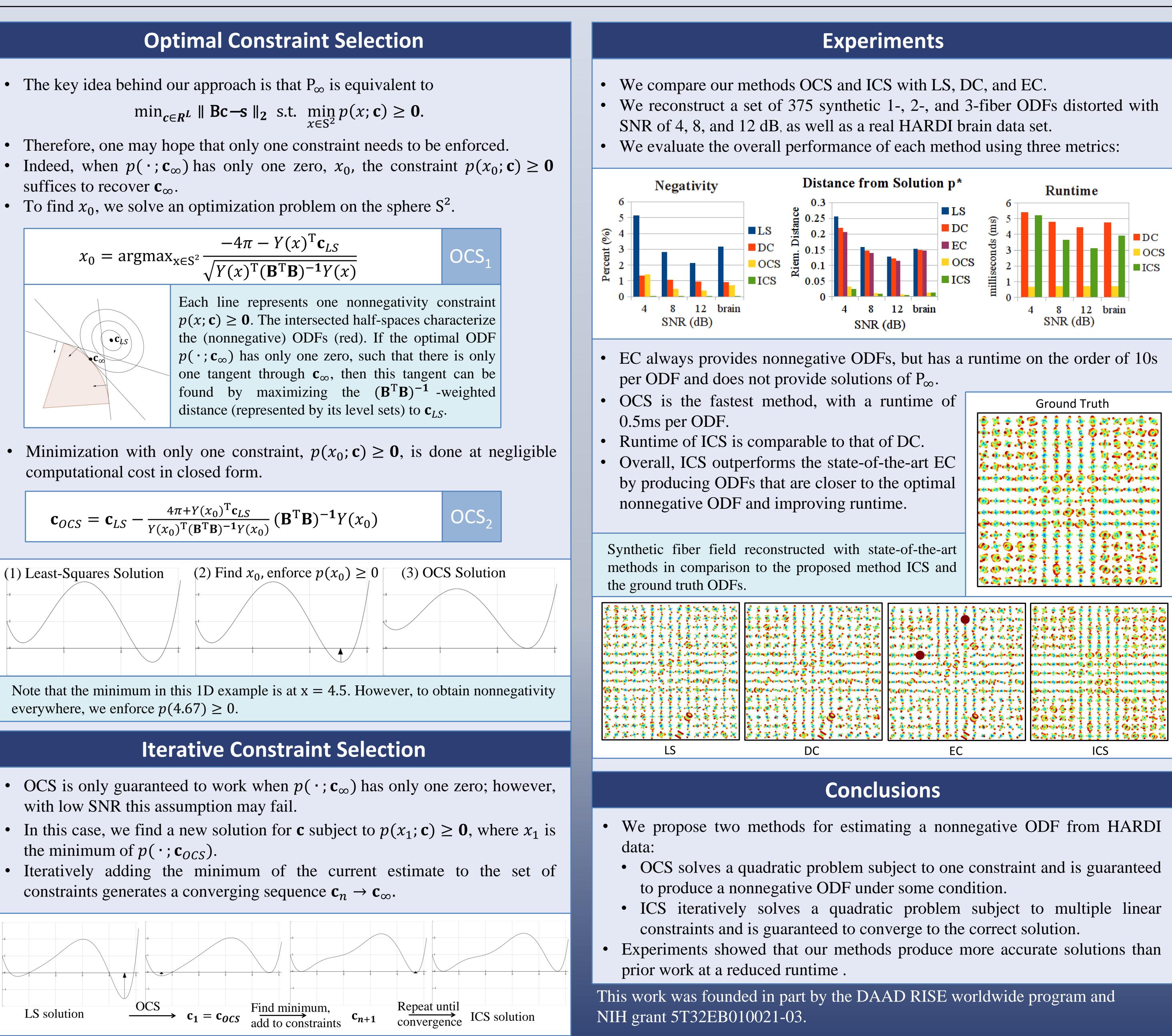
NONNEGATIVE ODF ESTIMATION VIA OPTIMAL CONSTRAINT SELECTION

Sören Wolfers, Evan Schwab, and René Vidal **Center for Imaging Science** Johns Hopkins University, Baltimore MD, USA

$$= \operatorname{argmax}_{x \in S^{2}} \frac{-4\pi - Y(x)^{\mathrm{T}} \mathbf{c}_{LS}}{\sqrt{Y(x)^{\mathrm{T}} (\mathbf{B}^{\mathrm{T}} \mathbf{B})^{-1} Y(x)^{\mathrm{T}} (\mathbf{B}^{\mathrm{T}} \mathbf{B})^{-1} Y(x)^{T$$

computational cost in closed form.





$$\approx Bc$$

$$c_j \lambda_j l_j Y_j(x)$$



