HW 1: Advanced Topics in Machine Learning

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Due 2/17/10 in class

- 1. If $S \in \mathbb{R}^{n \times n}$ is a real symmetric matrix then prove that:
 - (a) All eigenvalues of S Are real, i.e., $\sigma(S) \subset \mathbb{R}$.
 - (b) Let (λ, v) be an eigenvalue-eigenvector pair. If λ_i ≠ λ_j, then v_i ⊥ v_j; i.e., eigenvectors corresponding to distinct eigenvalues are orthogonal.
 - (c) There always exist n orthonormal eigenvectors of S, which form a basis of \mathbb{R}^n .
 - (d) S > 0 (S ≥ 0) if λ_i > 0 (λ_i ≥ 0) ∀i = 1, 2, ..., n; i.e., S is positive (semi-)definite if all eigenvalues are positive (non-negative).
 - (e) If $S \ge 0$ and $\lambda_1 \ge \lambda_2 \ge \ldots \ge \lambda_n$, then $\max_{\|x\|_2=1} < x$, $Sx \ge \lambda_1$ and $\min_{\|x\|_2=1} < x$, $Sx \ge \lambda_n$.
- 2. Prove the following:
 - (a) Consider the problem Ax = b with $A \in \mathbb{R}^{m \times n}$ of rank $p \le r \triangleq \min\{m, n\}$. Prove that the solution x^* that minimizes $||Ax b||_2$ is given by $x^* = A^{\dagger}b$, where A^{\dagger} is the generalized (Moore Penrose) inverse.
 - (b) Let $A = U\Sigma V^T$ be the SVD of A. Let $B = U\Sigma_p V^T$, where Σ_p denotes the matrix obtained from Σ by setting to zero its elements on the diagonal after the p^{th} entry. Show that $||A B||_F^2 = \sigma_{p+1}^2 + \ldots + \sigma_r^2$, where $|| \cdot ||_F$ indicates the Frobenius norm. Furthermore, show that such a norm is the minimum achievable over all matrices $B \in \mathbb{R}^{m \times n}$ of rank p, i.e.,

$$\min_{B:\operatorname{rank}(B)=p} \|A - B\|_F^2 = \sigma_{p+1}^2 + \ldots + \sigma_r^2.$$

3. Let x be a random vector with covariance matrix Σ_x . Consider a linear transformation of x:

$$\boldsymbol{y} = \boldsymbol{W}^{\top} \boldsymbol{x},\tag{1}$$

where $\boldsymbol{y} \in \mathbb{R}^d$ and W is a $D \times d$ orthogonal matrix, i.e., $W^\top W = I_d$. Let $\Sigma_{\boldsymbol{y}} = W^\top \Sigma_{\boldsymbol{x}} W$ be the covariance matrix for \boldsymbol{y} . Show that

- (a) The trace of Σ_{y} is maximized by $W = U_d$, where U_d consists of the first d (normalized) eigenvectors of Σ_{x} .
- (b) The trace of $\Sigma_{\boldsymbol{y}}$ is minimized by $W = \tilde{U}_d$, where \tilde{U}_d consists of the last d (normalized) eigenvectors of $\Sigma_{\boldsymbol{x}}$.
- 4. Given two d-dimensional subspaces S₁ and S₂ in ℝ^D, define the largest subspace angle θ₁ between S₁ and S₂ to be the largest possible sharp angle (< 90°) formed by any two vectors u₁, u₂ ∈ (S₁ ∩ S₂)[⊥] with u₁ ∈ S₁ and u₂ ∈ S₂ respectively. Let U₁ ∈ ℝ^{D×d} be an orthogonal matrix whose columns form a basis for S₁ and similarly U₂ for S₂. Then show that if σ₁ is the smallest non-zero singular value of the matrix W = U₁[⊤]U₂, then we have

$$\cos(\theta_1) = \sigma_1. \tag{2}$$

Similarly, one can define the rest of the subspace angles as $\cos(\theta_i) = \sigma_i$, i = 2, ..., d from the rest of the singular values of W.

Hint: Following the derivation of statistical PCA, find first the smallest angle (largest cosine = largest variance) and then find the second smallest angle all the way to the largest angle (smallest variance). As your proceed, the

vectors that achieve the second smallest angle need to be chosen to be perpendicular to the vectors that achieve the smallest angle and so forth, as we did in statistical PCA. Also, let $u_1 = U_1c_1$ and $u_2 = U_2c_2$. Show that you need to optimize $\cos(\theta) = c_1^{\top}U_1^{\top}U_2c_2$ subject to $||c_1|| = ||c_2|| = 1$. Show (using Lagrange multipliers) that a necessary condition for optimality is

$$\begin{bmatrix} 0 & U_1^\top U_2 \\ U_2^\top U_1 & 0 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \lambda \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}.$$
(3)

Deduce from here that $\sigma = \lambda^2$ is a singular value of $U_1^{\top}U_2$ with c_2 as singular vector.

- 5. (a) PowerFactorization can be used to compute the principal components of a zero-mean dataset with missing entries. How would you modify the method to deal with the case where the data is not zero mean?
 - (b) Implement PowerFactorization for nonzero mean data with missing entries. Use the following format

Function [x,U,Y]	= pf(X,d,W)
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Parameters

- X $D \times N$ matrix whose columns are the data points
- d dimension of low-dimensional representation
- \mathbb{W} D × N matrix whose ij entry is equal to 1 if Xij is given and to 0 if Xij is missing

Returned values

- \times D \times 1 vector containing the mean of the data
- \cup D × d matrix containing the basis for the subspace
- Y $d \times N$ matrix containing the principal components
- (c) Generate and plot a dataset X with D = 3; d = 2; N = 100; x=ones (D, 1);

[Q, R] =qr (randn (D, d)); U=Q(:, 1:d); Y=randn (d, N); Y=Y-mean (Y, 2) *ones (1, N); X=x*ones (1, N) +U*diag (3* (0:d-1)+1)*Y; plot3 (X(1,:), X(2,:), X(3,:),'.') Compute the mean and principal components of the dataset

x=mean(X,2); [U,S,V]=svd(X-x*ones(1,N)); U=U(:,1:d); Y=S(1:d,1:d)*V(:,1:d)'; Apply pf with W1=ones(D,N); [x1,U1,Y1]=pf(X,d,W1). Do you get the same results as PCA? Apply pf with W2=ones(D,N)-eye(D,N); [x2,U2,Y2]=pf(X,d,W2). Do you get the same results as PCA? Can you reconstruct the missing entries in X perfectly or approximately?

Plot the low-dimensional representations Y, Y1, Y2 and comment on their similarities and differences figure (1), plot(Y(1,:),Y(2,:),'or'); figure(2), plot(Y1(1,:),Y1(2,:),'xg'); figure(3), plot(Y2(1,:),Y2(2,:),'sb'); axis('equal');