

## Exam 2: Unsupervised Learning (600.692)

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1. **Manifold Learning.** Let  $\{\mathbf{x}_j \in \mathbb{R}^D\}_{j=1}^N$  be a set of points that lie approximately in a manifold of dimension  $d$  embedded in  $\mathbb{R}^D$ . Imagine you have applied KPCA with kernel  $\kappa$  and LLE with  $K$ -NN to the data. Assume now you are given a new point  $\mathbf{x} \in \mathbb{R}^D$  and you wish to find its corresponding point  $\mathbf{y} \in \mathbb{R}^d$  according to KPCA and LLE. How would you compute  $\mathbf{y} \in \mathbb{R}^d$  without applying KPCA or LLE from scratch to the  $N + 1$  points? Under what conditions the solution you propose is equivalent to applying KPCA or LLE to the  $N + 1$  points?
2. **K-Subspaces.** Consider the objective function of the K-subspaces algorithm:

$$f(\{\boldsymbol{\mu}_i\}_{i=1}^n, \{U_i\}_{i=1}^n) = \min_{\substack{\{\boldsymbol{\mu}_i\}_{i=1}^n \\ \{U_i: U_i^\top U_i = I\}_{i=1}^n}} \sum_{j=1}^N \min_{i=1, \dots, n} \|(I - U_i U_i^\top)(\mathbf{x}_j - \boldsymbol{\mu}_i)\|^2. \quad (1)$$

Let  $\{\boldsymbol{\mu}_i^{(k)}\}_{i=1}^n, \{U_i^{(k)}\}_{i=1}^n$  be the estimates of the subspace parameters at the  $k$ th iteration of the  $K$ -subspaces algorithm. Show that the iterations of  $K$ -subspaces are such that

$$f(\{\boldsymbol{\mu}_i^{(k+1)}\}_{i=1}^n, \{U_i^{(k+1)}\}_{i=1}^n) \leq f(\{\boldsymbol{\mu}_i^{(k)}\}_{i=1}^n, \{U_i^{(k)}\}_{i=1}^n). \quad (2)$$

3. **Low-Rank Subspace Clustering.** Let  $X = [\mathbf{x}_1, \dots, \mathbf{x}_N] \in \mathbb{R}^{D \times N}$  be a data matrix whose columns are drawn from a union of  $n$  subspaces. Let  $X = U \Sigma V^\top$  and  $X = U_1 \Sigma_1 V_1^\top$  be, respectively, the full and compact SVDs of  $X$ , with  $V$  partitioned as  $[V_1, V_2]$ , where  $V_1 \in \mathbb{R}^{N \times r}$ ,  $V_2 \in \mathbb{R}^{N \times (N-r)}$  and  $\text{rank}(X) = r$ . Let us express each data point as a linear combination of all data points, i.e., for all  $j$ ,  $\mathbf{x}_j = \sum_{i=1}^N \mathbf{x}_i c_{ij}$ , or equivalently  $\mathbf{x}_j = X \mathbf{c}_j$ , where  $\mathbf{c}_j \in \mathbb{R}^N$ . Let us now search for a matrix of coefficients  $C = [\mathbf{c}_1, \dots, \mathbf{c}_N] \in \mathbb{R}^{N \times N}$  that solves the following optimization problem:

$$\min_C \|C\|_* + \frac{\lambda}{2} \|C\|_F^2 \quad \text{s.t. } X = XC \quad \text{and} \quad C = C^\top, \quad (3)$$

where  $\lambda > 0$  is a parameter. Prove that  $C^* = V_1 V_1^\top$ .

**Hint:** We showed in class that the solutions to  $X = XC$  are of the form  $C = V_1 V_1^\top + V_2 A$ , for  $A \in \mathbb{R}^{(N-r) \times N}$ .