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# Generalized Principal Component Analysis for Image Representation & Segmentation

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INTRODUCTION

GPCA FOR LOSSY IMAGE REPRESENTATION

IMAGE SEGMENTATION VIA LOSSY COMPRESSION

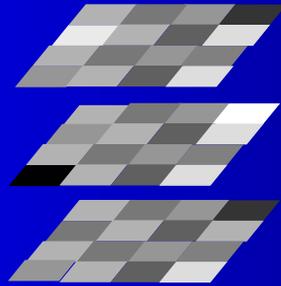
OTHER APPLICATIONS

CONCLUSIONS AND FUTURE DIRECTIONS

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# Introduction – Image Representation via Linear Transformations

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better  
representations?

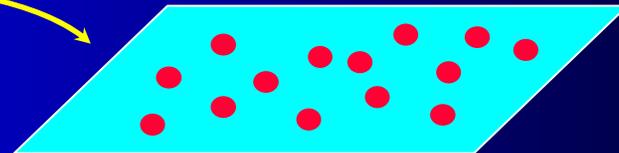
pixel-based representation  
three matrixes of RGB-values



linear transformation

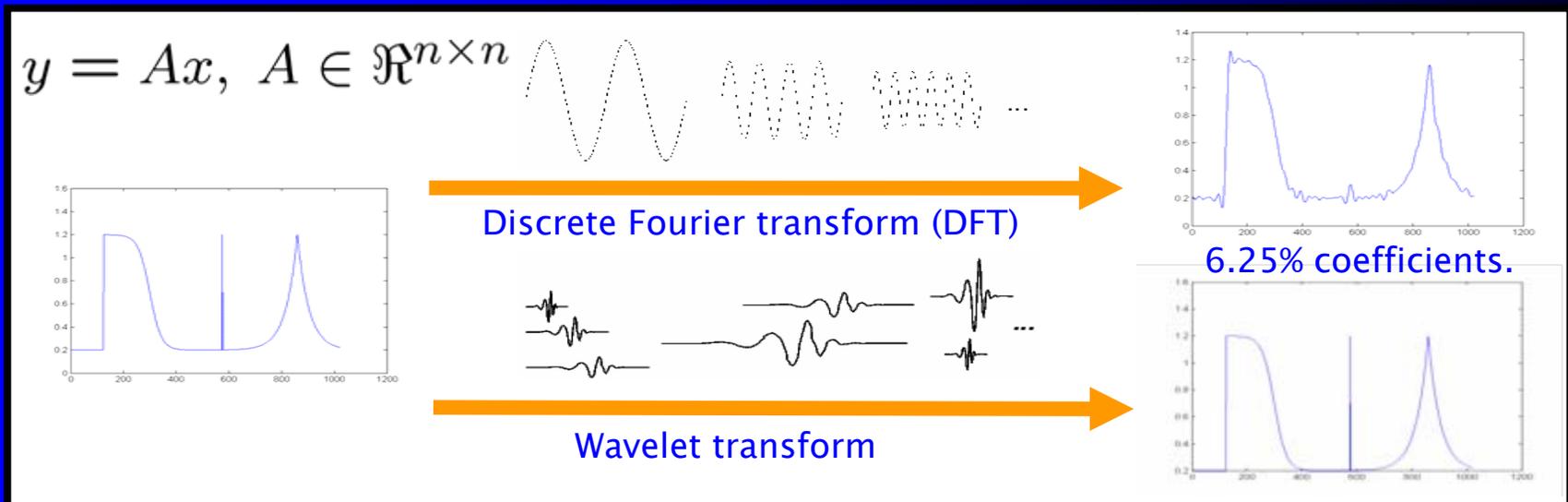


a more compact  
representation



# Introduction

- Fixed Orthogonal Bases (representation, approximation, compression)
- Discrete Fourier transform (DFT) or discrete cosine transform (DCT) (Ahmed '74): JPEG.
  - Wavelets (multi-resolution) (Daubechies'88, Mallat'92): JPEG-2000.
  - Curvelets and contourlets (Candes & Donoho'99, Do & Vetterli'00)



Unorthogonal Bases (for redundant representations)

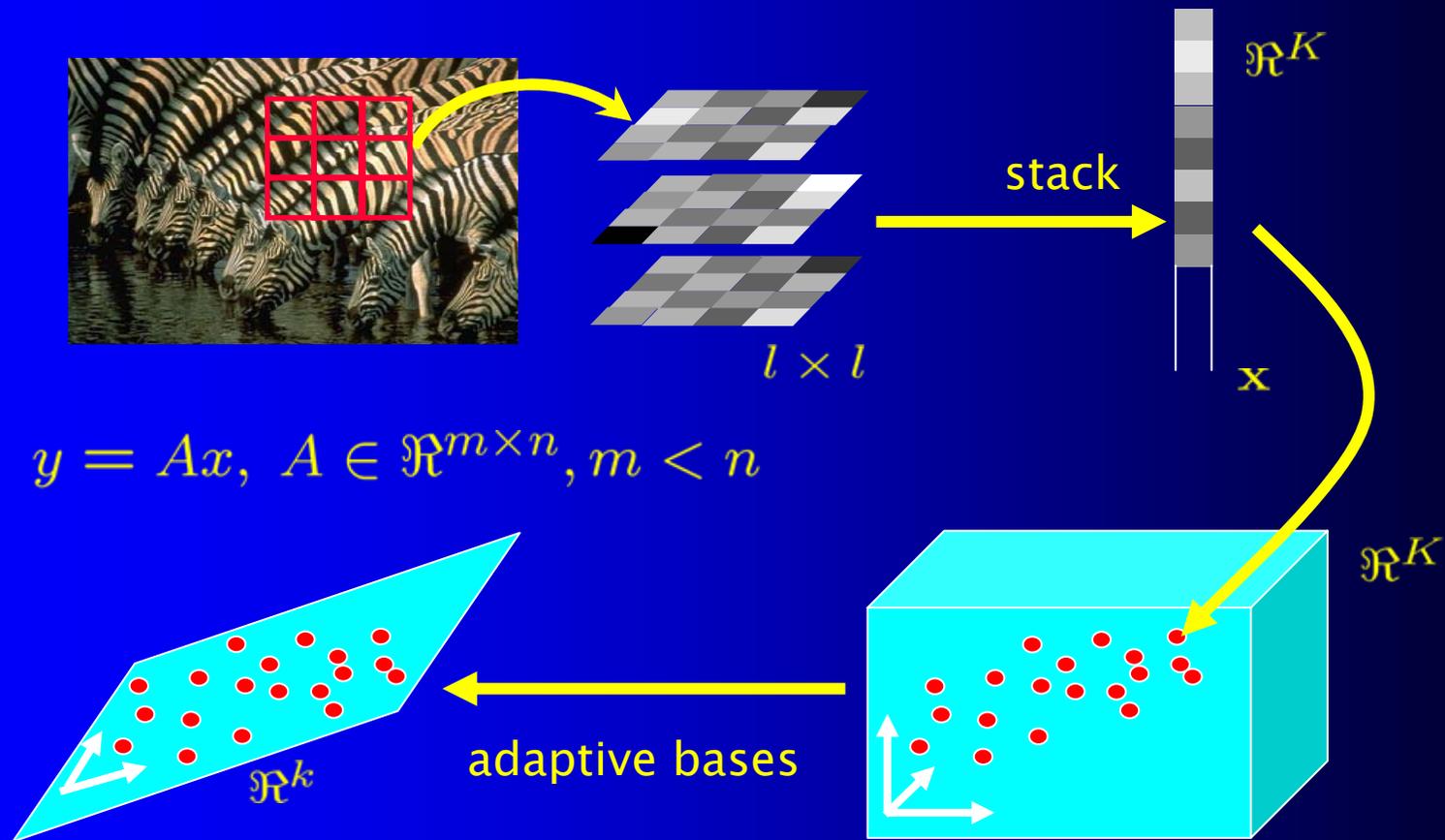
- Extended lapped transforms, frames, sparse representations ( $L^p$  geometry)

$$\min |x|, \text{ s.t. } y = Ax, A \in \mathbb{R}^{n \times m}, m > n$$

# Introduction

Adaptive Bases (optimal if imagery data are uni-modal)

- Karhunen-Loeve transform (KLT), also known as PCA (Pearson'1901, Hotelling'33, Jolliffe'86)



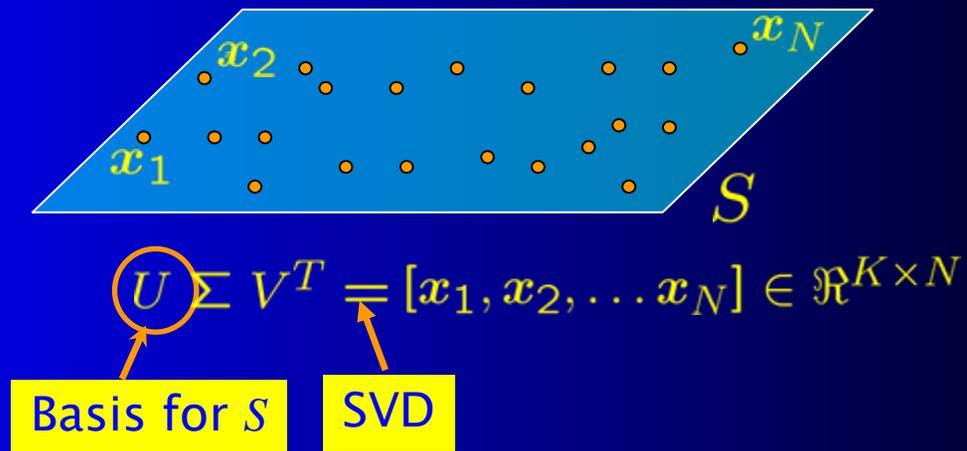
# Introduction – Principal Component Analysis (PCA)

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## Dimensionality Reduction

*Find a low-dimensional representation (model) for high-dimensional data.*

Principal Component Analysis (Pearson'1901, Hotelling'1933, Eckart & Young'1936) or Karhunen–Loeve transform (KLT).

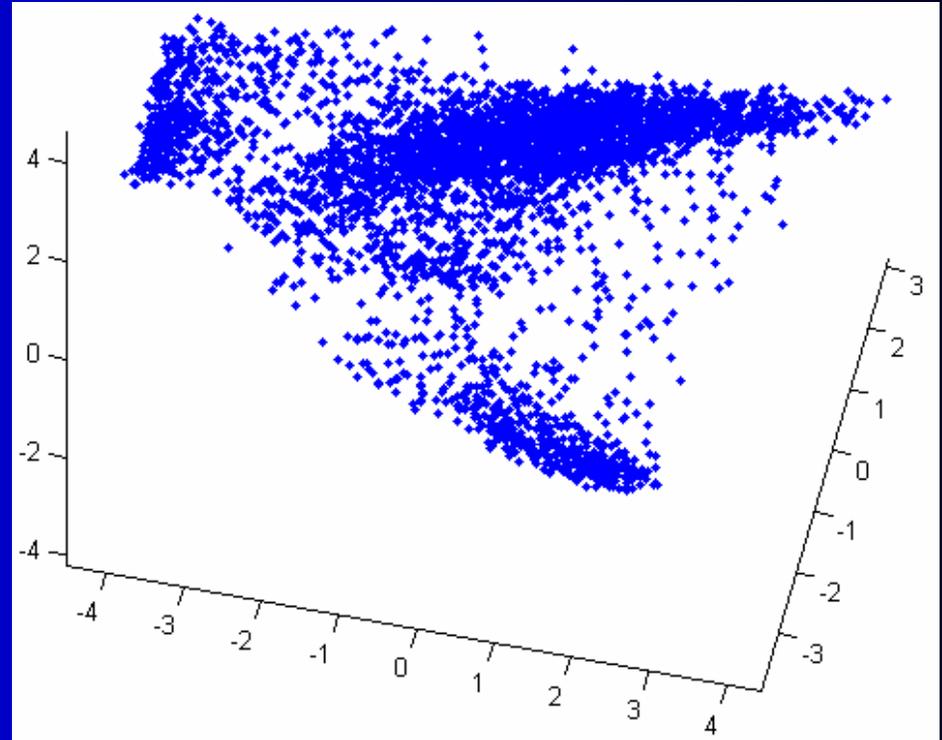
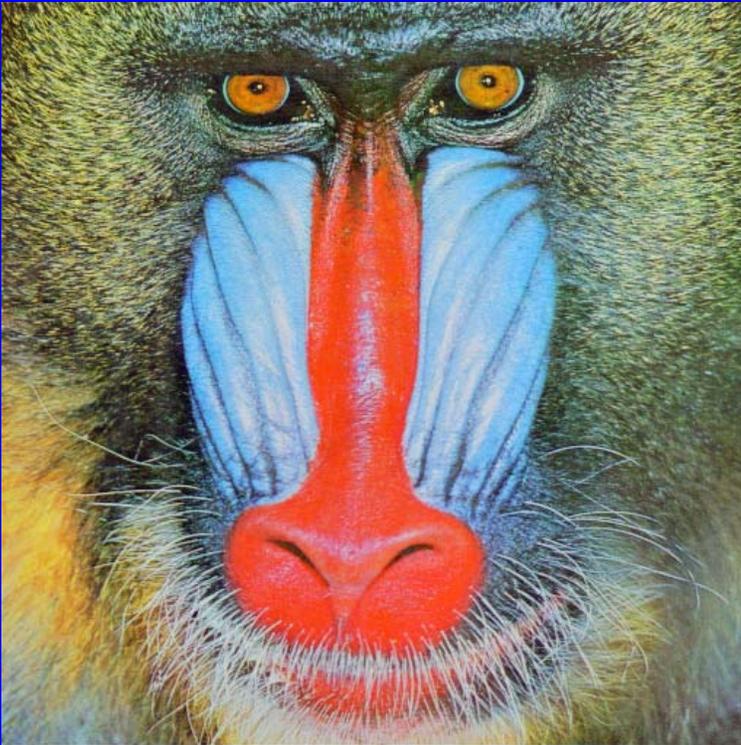


## Variations of PCA

- Nonlinear Kernel PCA (Scholkopf–Smola–Muller'98)
  - Probabilistic PCA (Tipping–Bishop'99, Collins et.al'01)
  - Higher–Order SVD (HOSVD) (Tucker'66, Davis'02)
  - Independent Component Analysis (Hyvarinen–Karhunen–Oja'01)
-

## Hybrid Linear Models – Multi-Modal Characteristics

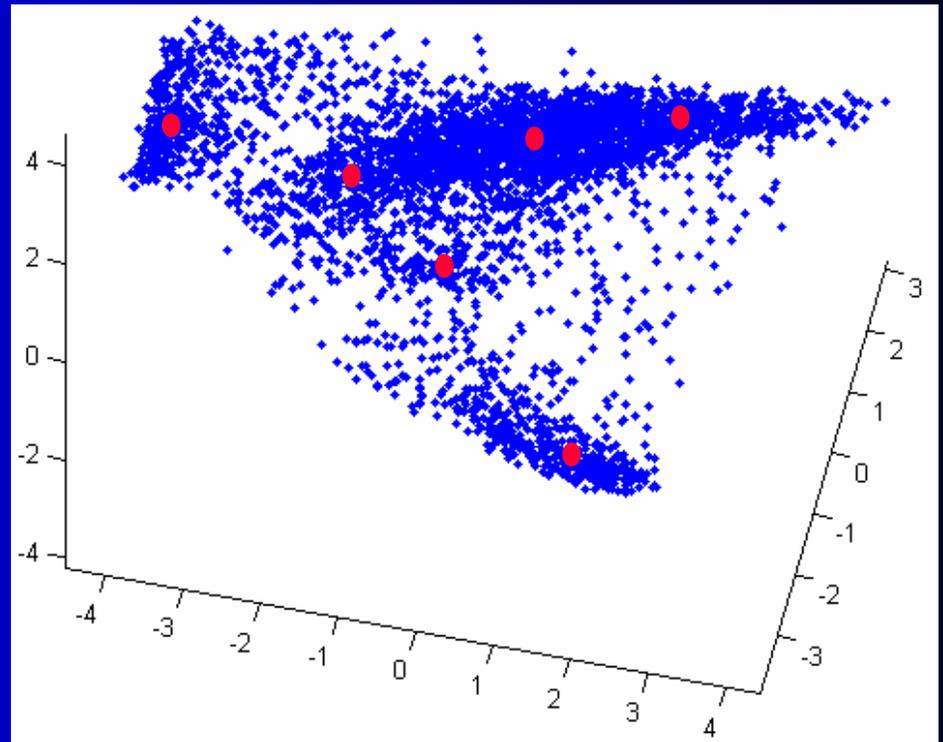
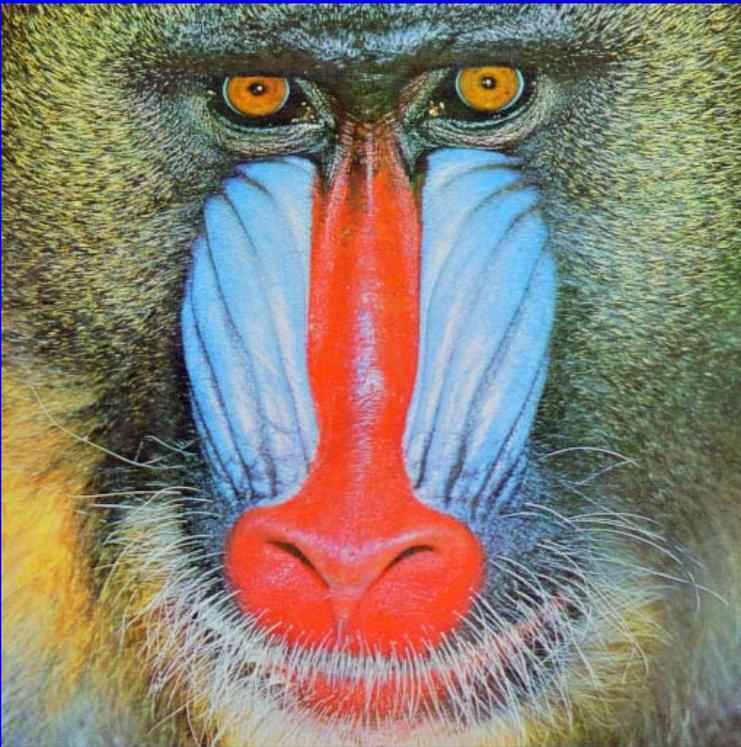
Distribution of the first three principal components of the Baboon image: A clear **multi-modal** distribution



# Hybrid Linear Models – Multi-Modal Characteristics

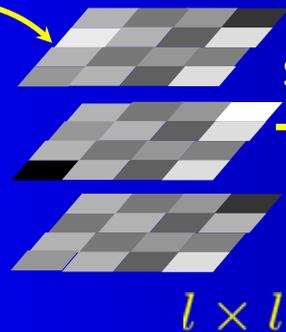
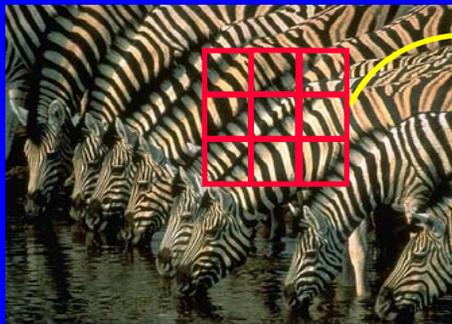
## Vector Quantization (VQ)

- multiple 0-dimensional affine subspaces (i.e. cluster means)
- existing clustering algorithms are iterative (EM, K-means)

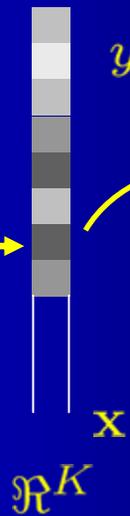


# Hybrid Linear Models – Versus Linear Models

## A single linear model

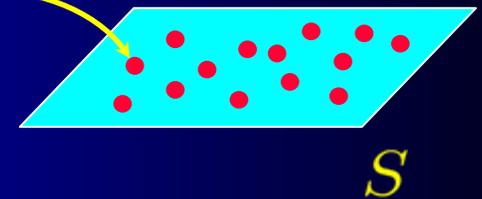


stack

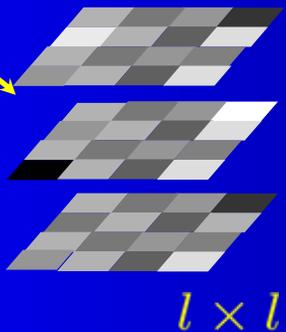
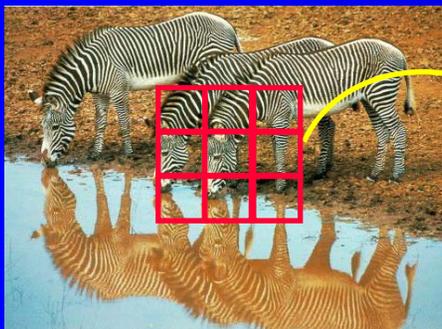


$$y = Ax, A \in \mathbb{R}^{m \times n}, m < n$$

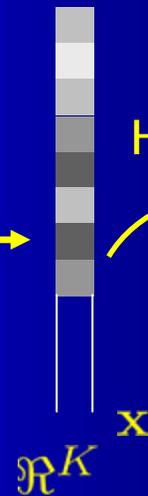
Linear



## Hybrid linear models

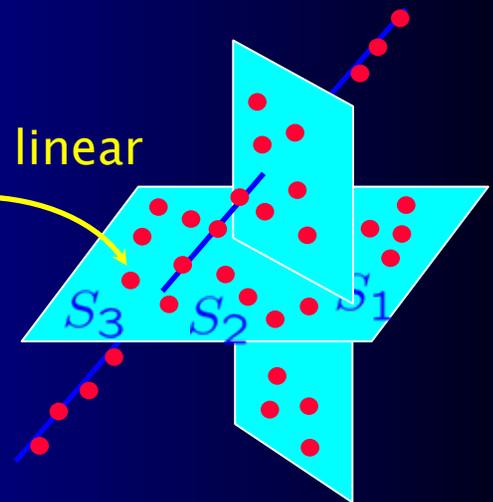


stack



Hybrid linear

$$y = A_i x, A_i \in \mathbb{R}^{m_i \times n}, m_i < m < n$$



## Hybrid Linear Models – Characteristics of Natural Images

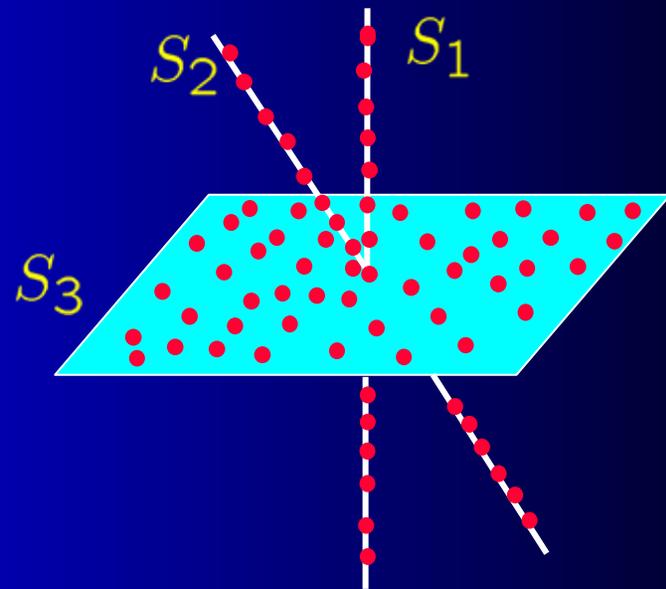
	Multivariate		Hybrid (multi-modal)	Hierarchical (multi-scale)	High-dimensional (vector-valued)
	1D	2D			
Fourier (DCT)	X	X			
Wavelets	X			X	
Curvelets		X			
Random fields		X	X	X	
PCA/KLT	X	X			X
VQ	X	X	X		X
Hybrid linear	X	X	X	X	X

We need a new & simple paradigm to effectively account for all these characteristics simultaneously.

# Hybrid Linear Models – Subspace Estimation and Segmentation

## Hybrid Linear Models (or Subspace Arrangements)

- the number of subspaces is unknown
- the dimensions of the subspaces are unknown
- the basis of the subspaces are unknown
- the segmentation of the data points is unknown

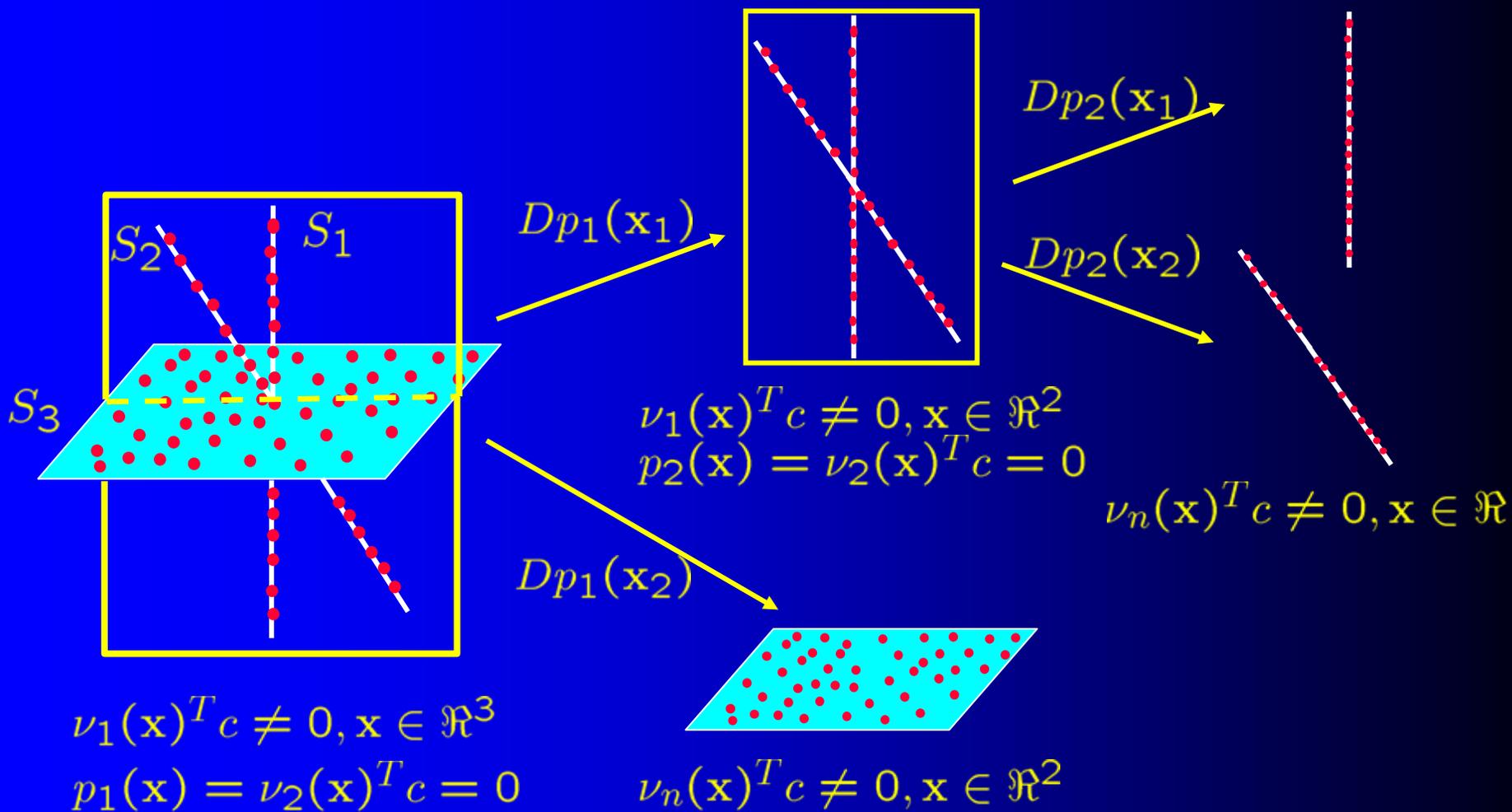


### “Chicken-and-Egg” Coupling

- Given segmentation, estimate subspaces
- Given subspaces, segment the data

# Hybrid Linear Models – Recursive GPCA (an Example)

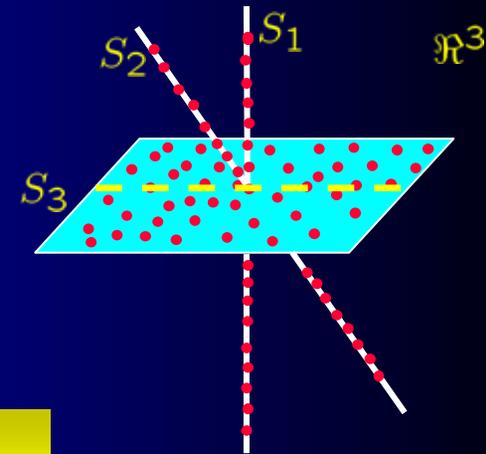
$$p(\mathbf{x}) = c_1 x_1^n + c_2 x_1^{n-1} x_2 + \dots + c_m x_3^n = \nu_n(\mathbf{x})^T c$$



# Hybrid Linear Models – Effective Dimension

## Model Selection (for Noisy Data)

- Model complexity;
- Data fidelity;



Number of subspaces

$$ED(X, S) = \frac{1}{N} \sum_1^s k_i (K - k_i) + \frac{1}{N} \sum_1^s N_i k_i$$

Total number of points

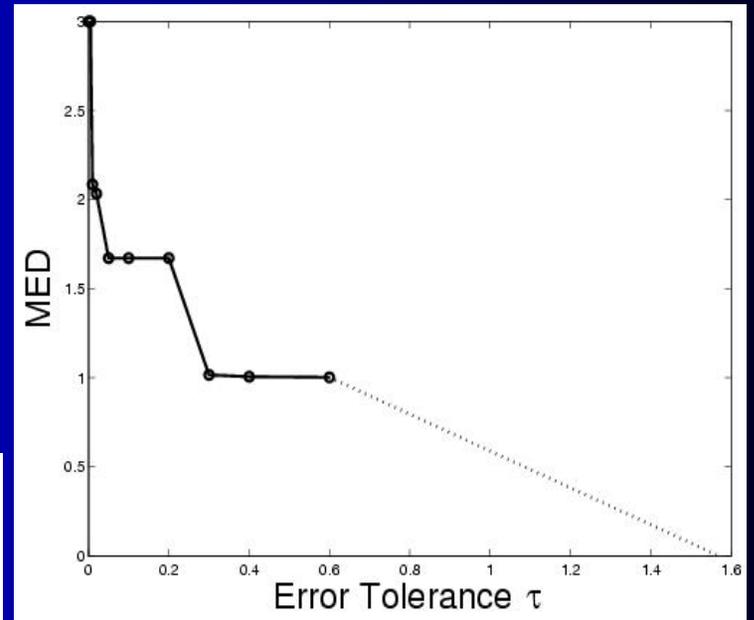
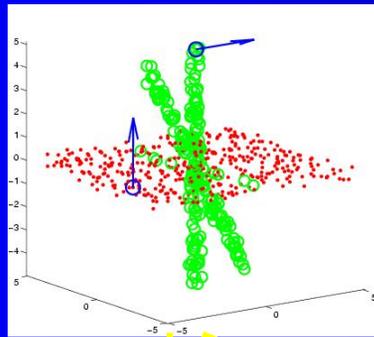
Dimension of each subspace

Number of points in each subspace

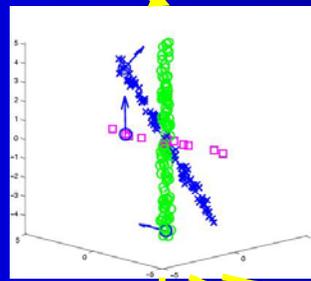
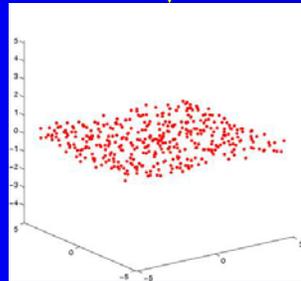
Model selection criterion: minimizing effective dimension subject to a given error tolerance (or PSNR)

# Hybrid Linear Models – Simulation Results (5% Noise)

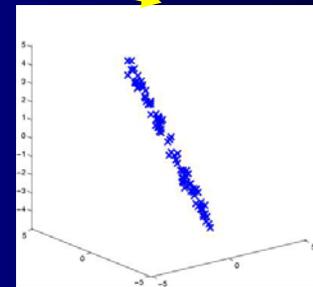
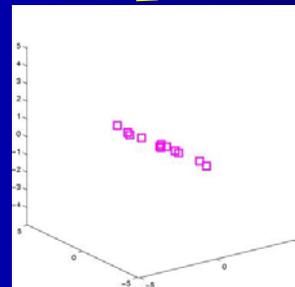
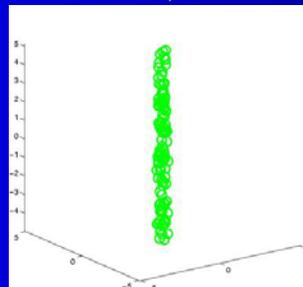
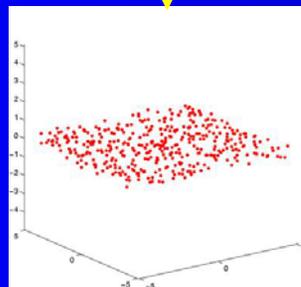
ED=3



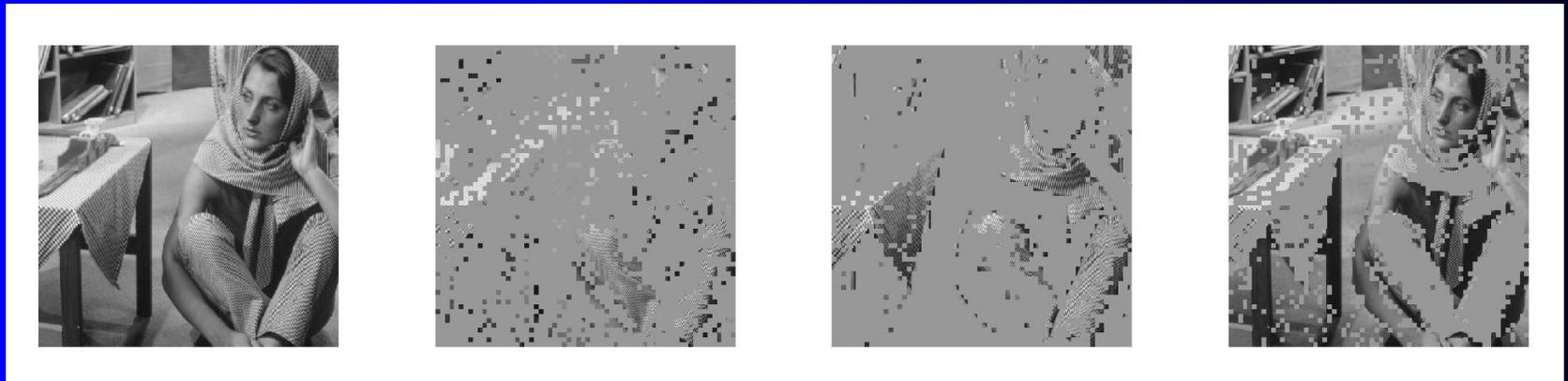
ED=2.0067



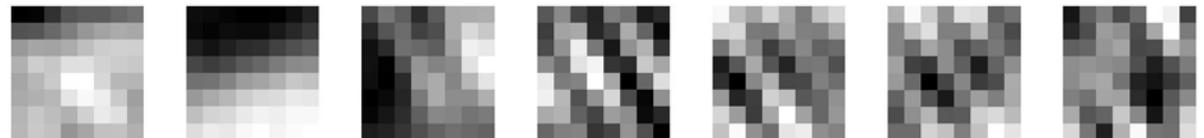
ED=1.6717



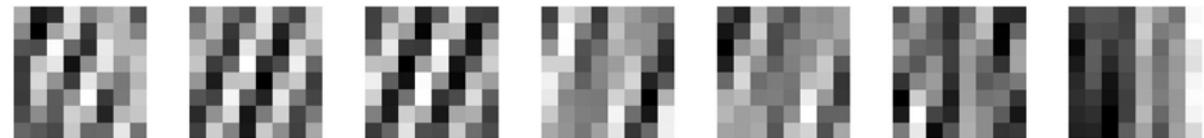
# Hybrid Linear Models – Subspaces of the Barbara Image



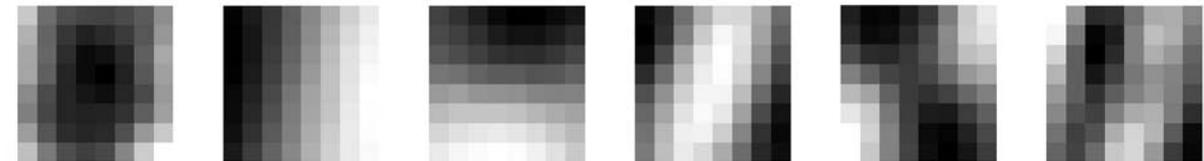
$S_1$



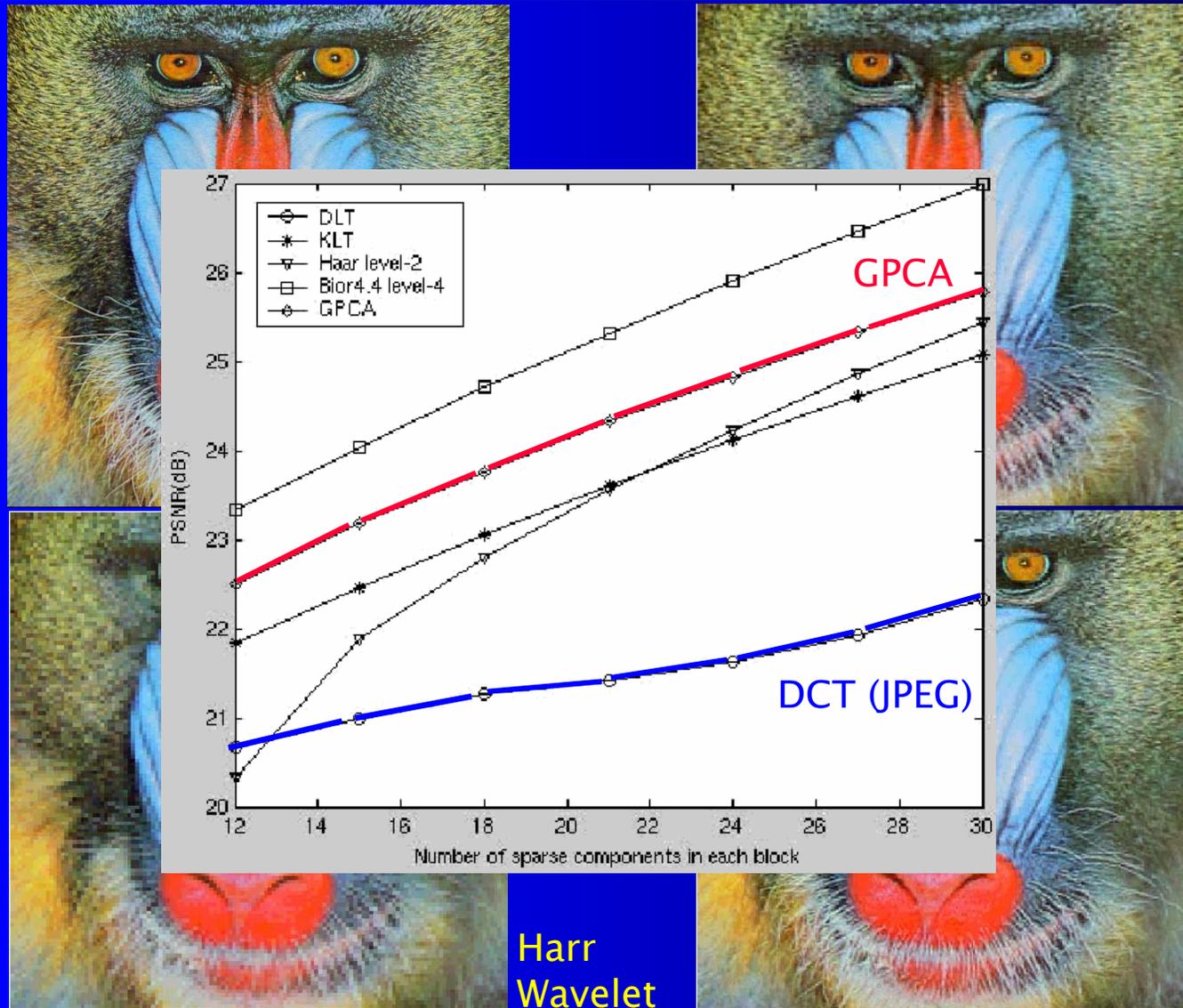
$S_2$



$S_3$



# Hybrid Linear Models – Lossy Image Representation (Baboon)



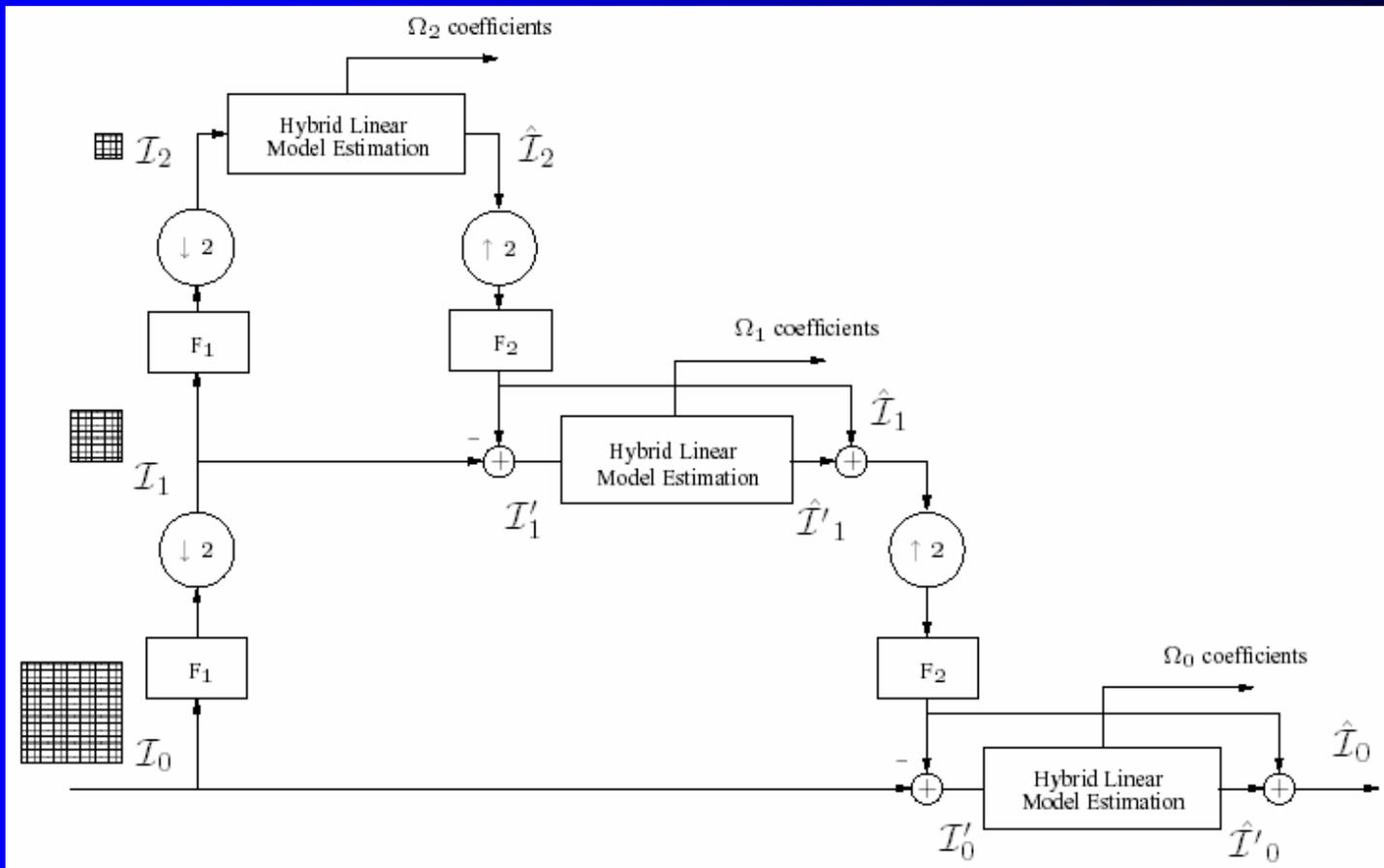
PCA (8x8)

Harr Wavelet

GPCA (8x8)

## Multi-Scale Implementation – Algorithm Diagram

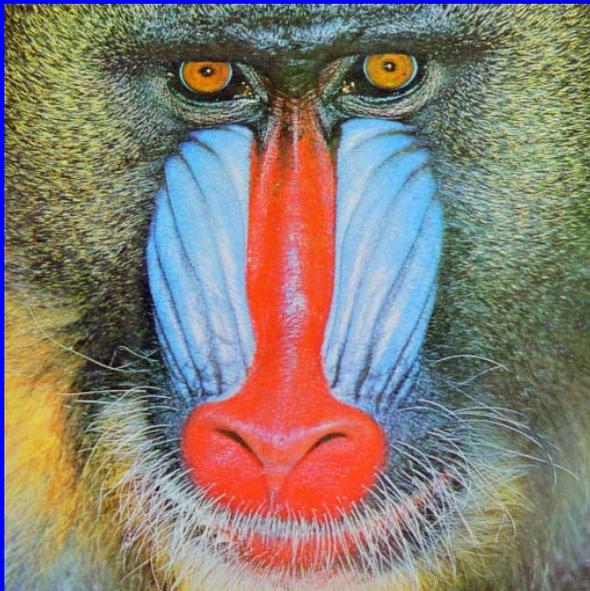
Diagram for a level-3 implementation of hybrid linear models for image representation



# Multi-Scale Implementation - The Baboon Image

The Baboon image

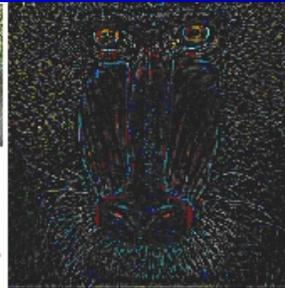
$\mathcal{I}$



$\mathcal{I}_2$

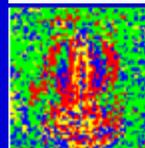


$\mathcal{I}'_1$

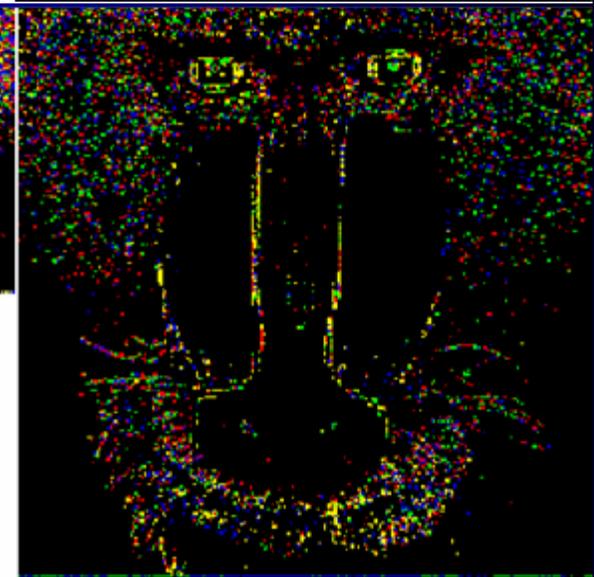


downsample  
by two twice

$\mathcal{I}'_0$

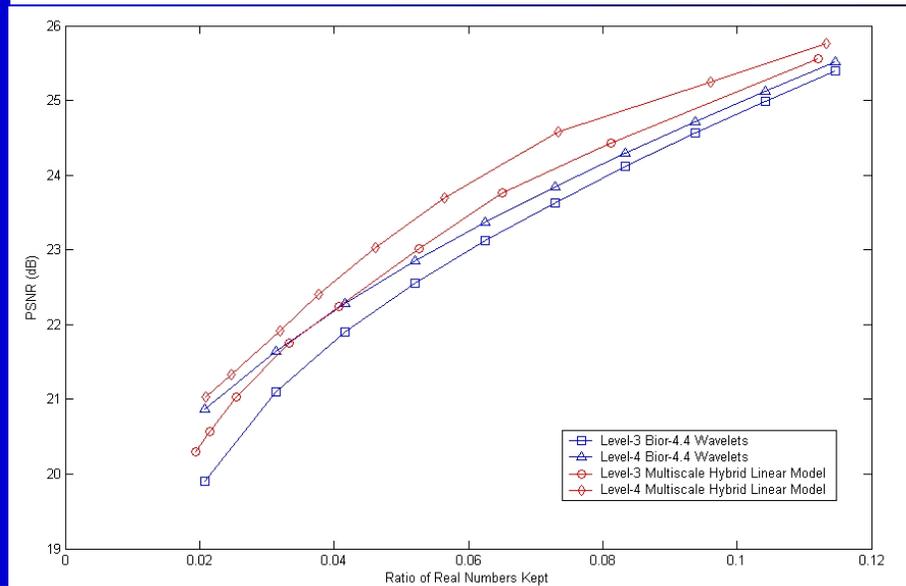
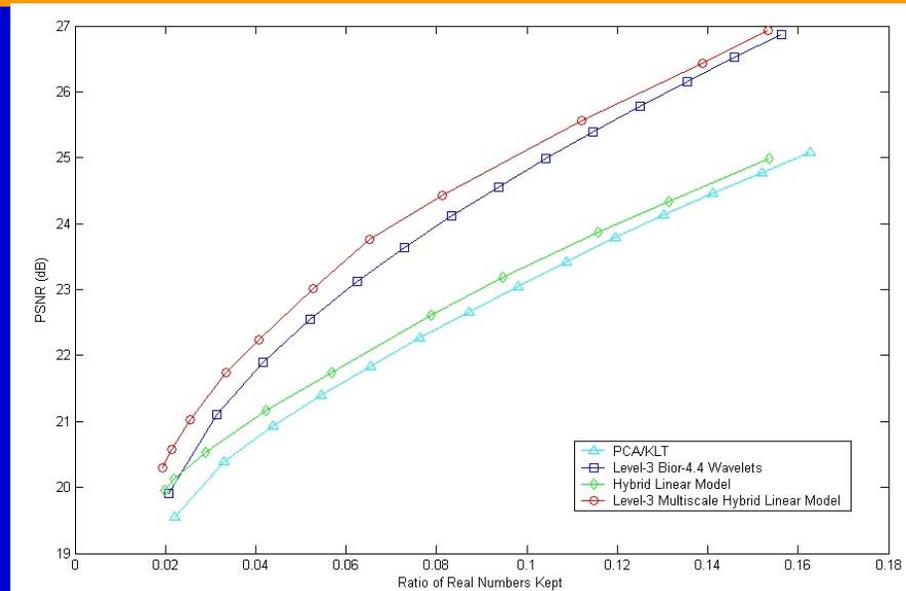
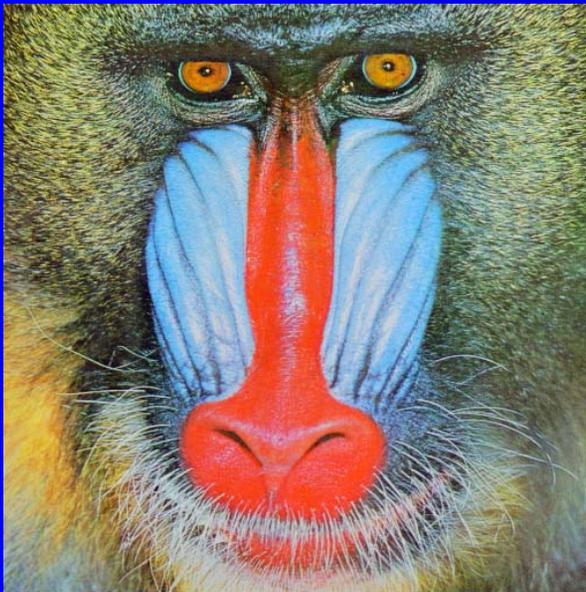


segmentation of  
2 by 2 blocks



# Multi-Scale Implementation – Comparison with Other Methods

The Baboon image

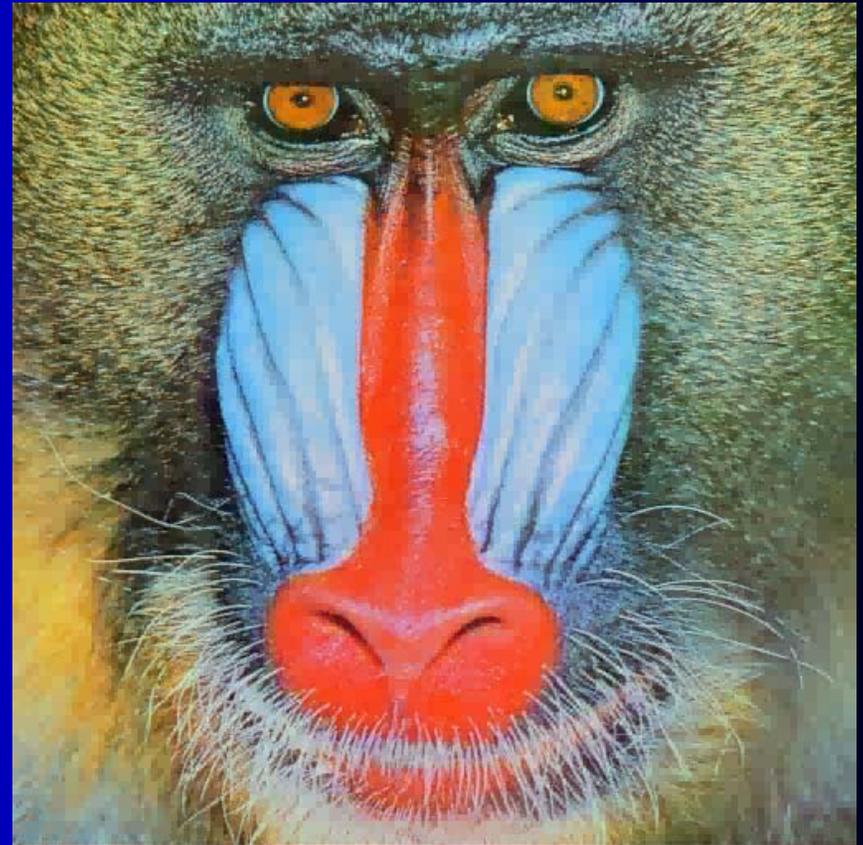


## Multi-Scale Implementation – Image Approximation

Comparison with level-3 wavelet (7.5% coefficients)



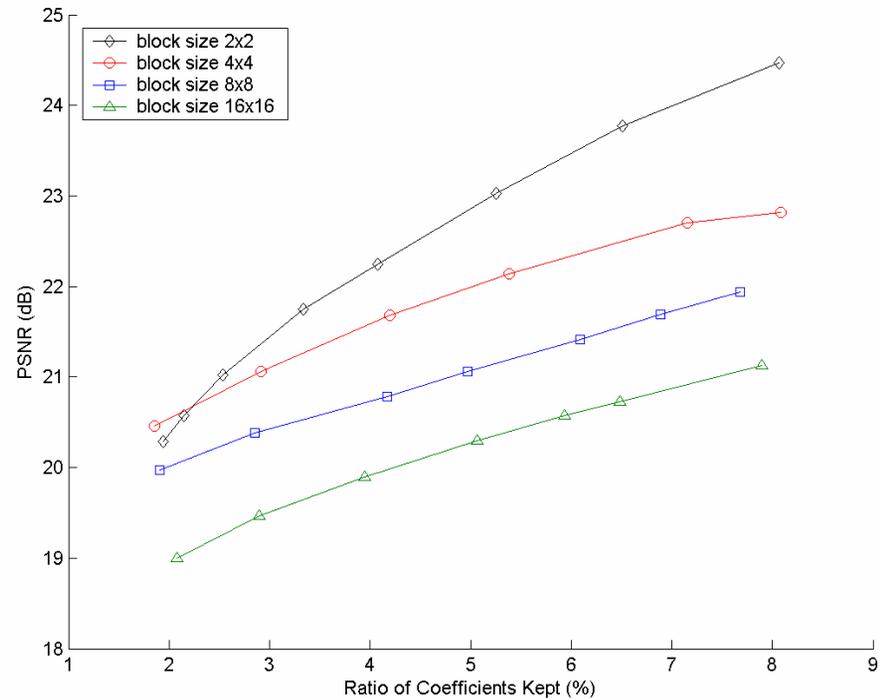
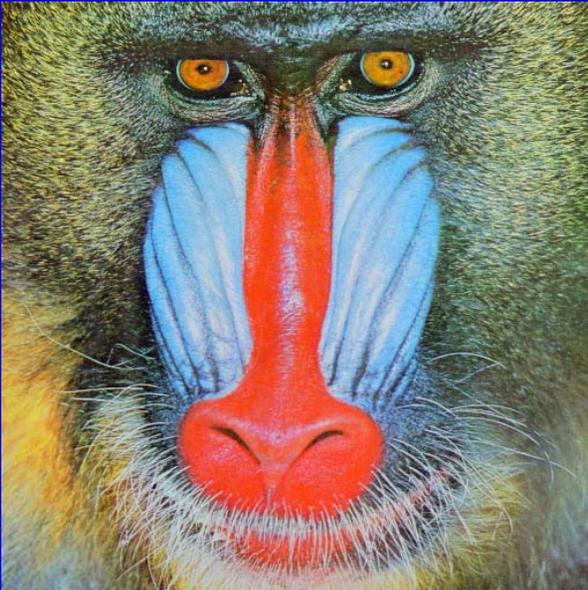
Level-3 bior-4.4 wavelets  
PSNR=23.94



Level-3 hybrid linear model  
PSNR=24.64

# Multi-Scale Implementation – Block Size Effect

The Baboon image

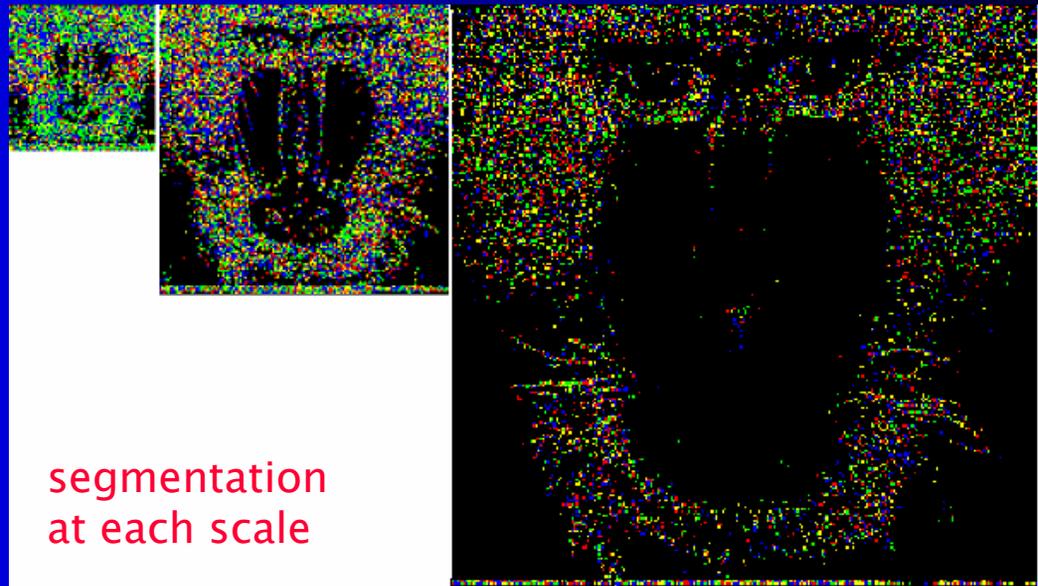
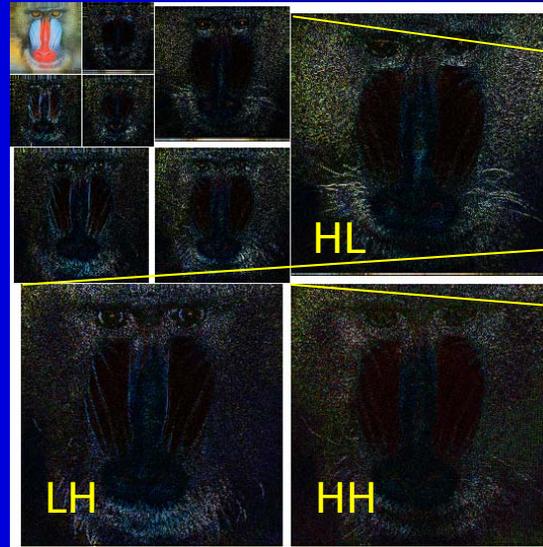
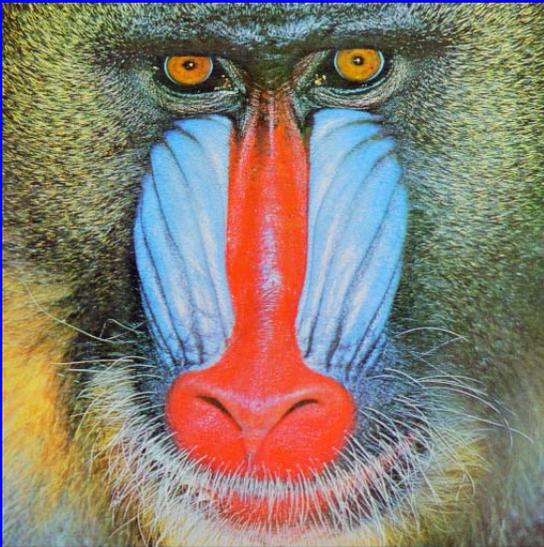


Some **problems** with the multi-scale hybrid linear model:

1. has minor block effect;
2. is computationally more costly (than Fourier, wavelets, PCA);
3. does not fully exploit spatial smoothness as wavelets.

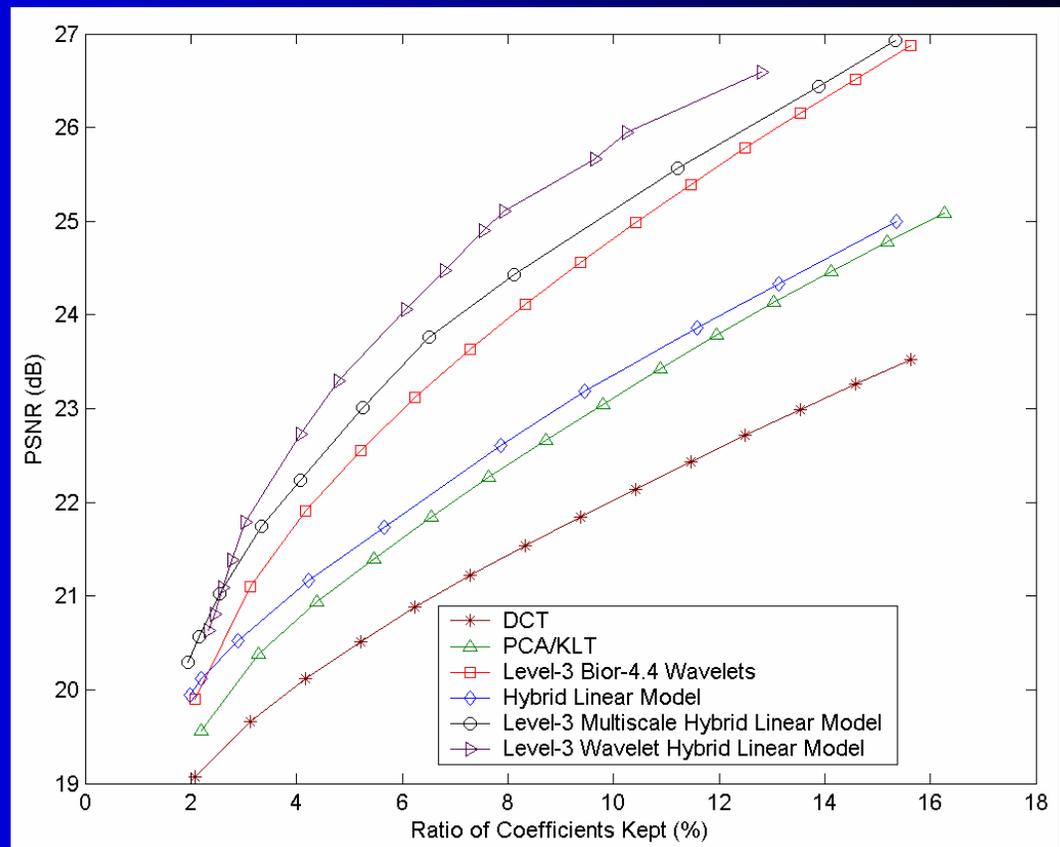
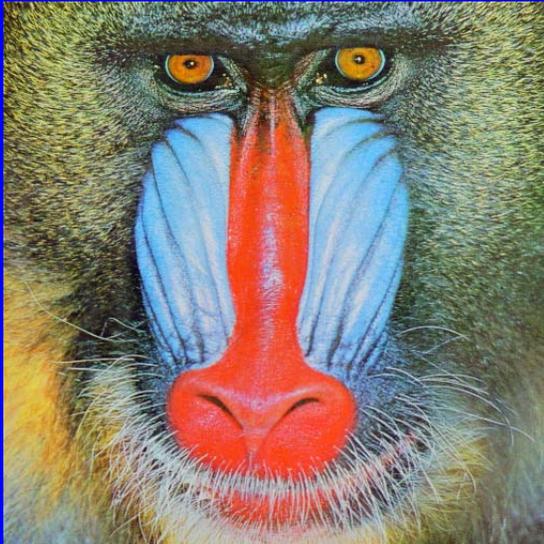
# Multi-Scale Implementation - The Wavelet Domain

The Baboon image



# Multi-Scale Implementation – Wavelets v.s. Hybrid Linear Wavelets

The Baboon image



Advantages of the hybrid linear model in wavelet domain:

1. eliminates block effect;
2. is computationally less costly (than in the spatial domain);
3. achieves higher PSNR.

## Multi-Scale Implementation – Visual Comparison

Comparison among several models (7.5% coefficients)

Original  
Image



Wavelets  
PSNR=23.94



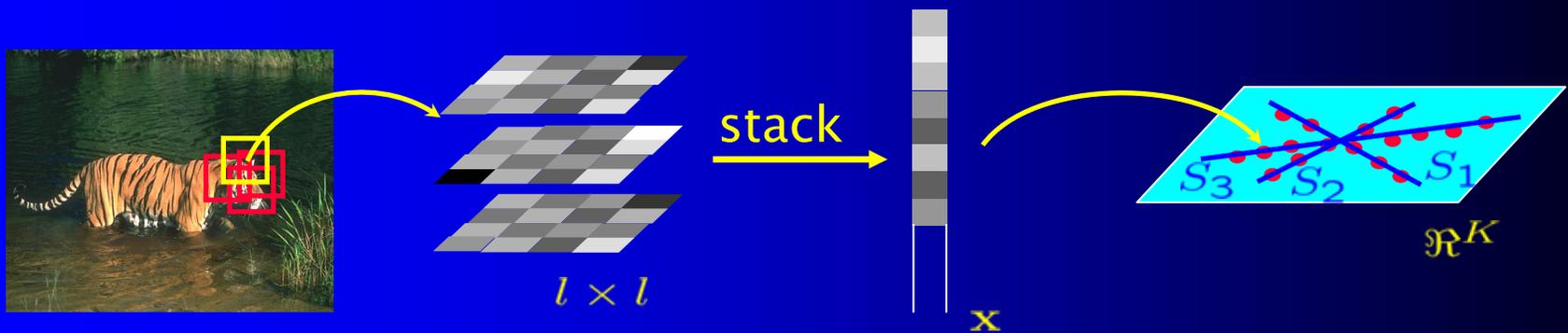
Hybrid model  
in spatial  
domain  
PSNR=24.64



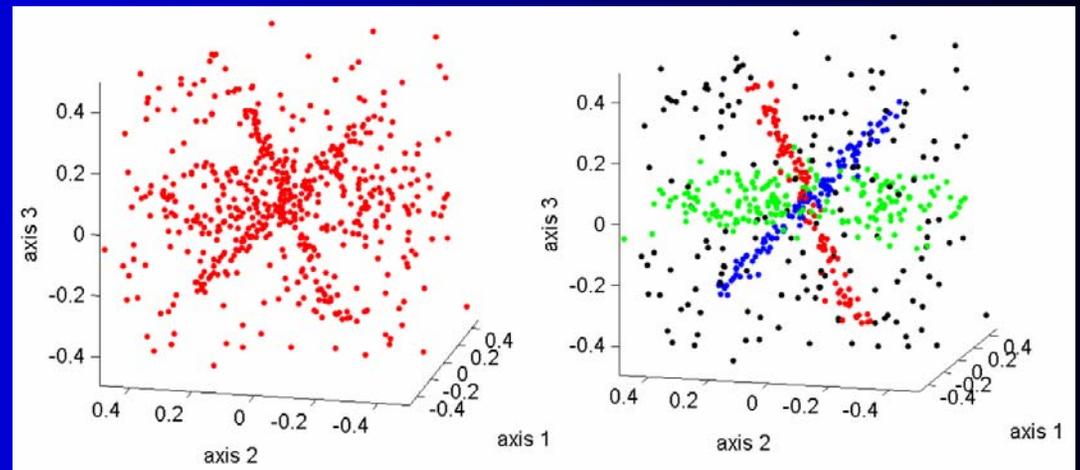
Hybrid model  
in wavelet  
domain  
PSNR=24.88



# Image Segmentation – via Lossy Data Compression



$$\min L^s(X) = L(X_1) + L(X_2) + \dots + L(X_n) + H(|X_1|, |X_2|, \dots, |X_n|).$$



QuickTime™ and a  
PNG decompressor  
are needed to see this picture.

## APPLICATIONS – Texture-Based Image Segmentation

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Naïve approach:

- Take a 7x7 Gaussian window around every pixel.
- Stack these windows as vectors.
- Clustering the vectors using our algorithm.

A few results:



## APPLICATIONS – Distribution of Texture Features

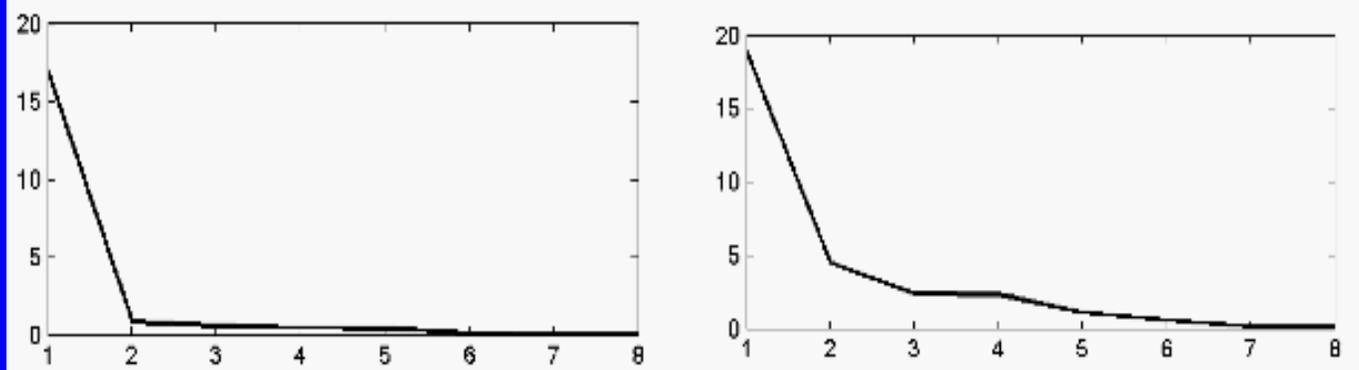
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**Question:** why does such a simple algorithm work at all?

**Answer:** Compression (MDL/MCL) is well suited to mid-level texture segmentation.

Using a **single representation** (e.g. windows, filterbank responses) for texture of different complexity  $\Rightarrow$  **redundancy and degeneracy**, which can be exploited for clustering / compression.

QuickTime™ and a  
TIFF (LZW) decompressor  
are needed to see this picture.



Above: singular values of feature vectors from two different segments of the image at left.

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# APPLICATIONS – Compression-based Texture Merging (CTM)

**Problem** with the naïve approach:

Strong edges, segment boundaries



**Solution:**

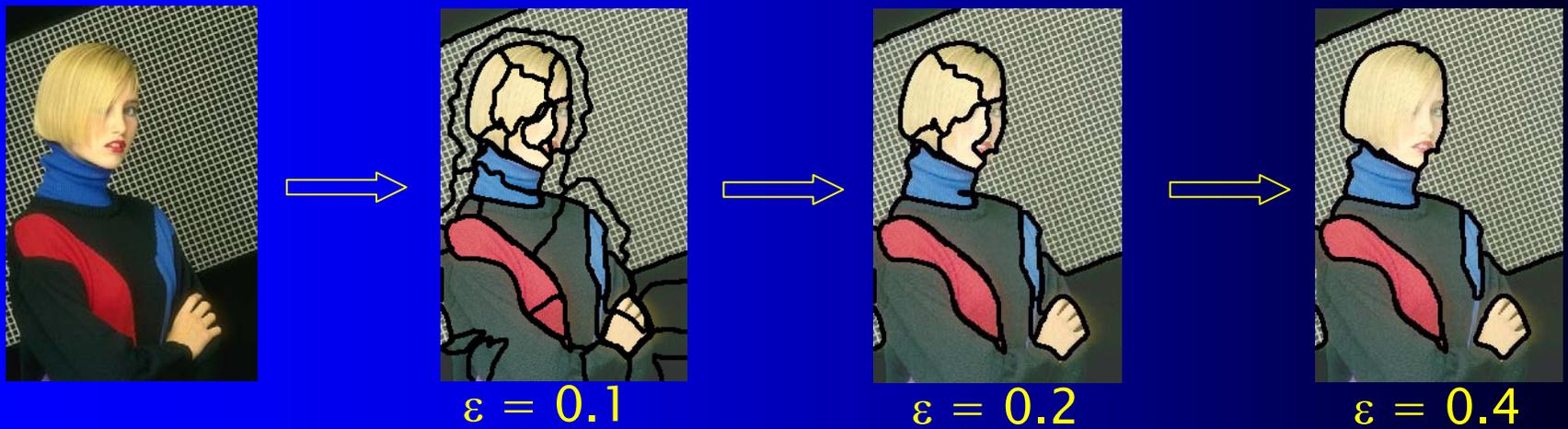
Low-level, edge-preserving over-segmentation into small homogeneous regions.

Simple features: stacked Gaussian windows (7x7 in our experiments).

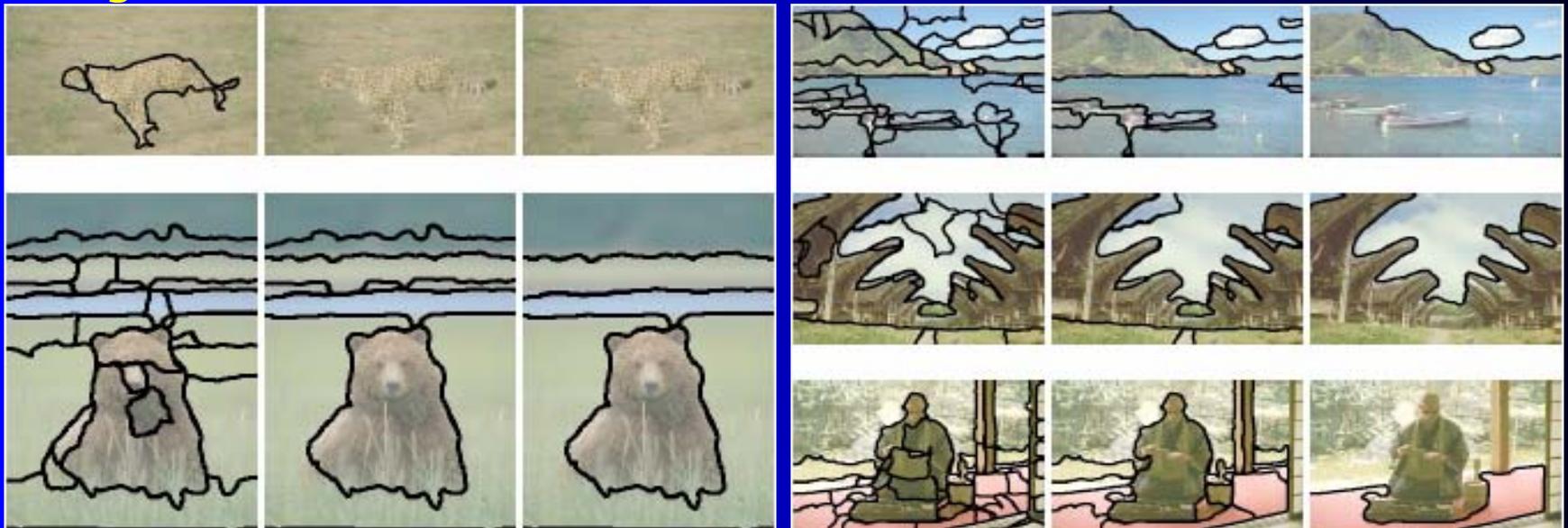
Merge adjacent regions to minimize coding length (“compress” the features).



# APPLICATIONS – Hierarchical Image Segmentation via CTM



Lossy coding with varying distortion  $\varepsilon \Rightarrow$  hierarchy of segmentations





## APPLICATIONS – CTM: Quantitative Evaluation and Comparison

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### Berkeley Image Segmentation Database

	PRI	VoI	GCE	BDE
Humans	0.8754	1.1040	0.0797	4.994
CTM (0.1)	0.7561	2.4640	<b>0.1767</b>	<b>9.4211</b>
CTM (0.15)	0.7627	2.2035	0.1846	9.4902
CTM (0.2)	0.7617	<b>2.0236</b>	0.1877	9.8962
Mean-Shift	0.7550	2.477	0.2598	9.7001
NCuts	0.7229	2.9329	0.2182	9.6038
FH	<b>0.7841</b>	2.6647	0.1895	9.9497

PRI: Probabilistic Rand Index [Pantofaru 2005]

Vol: Variation of Information [Meila 2005]

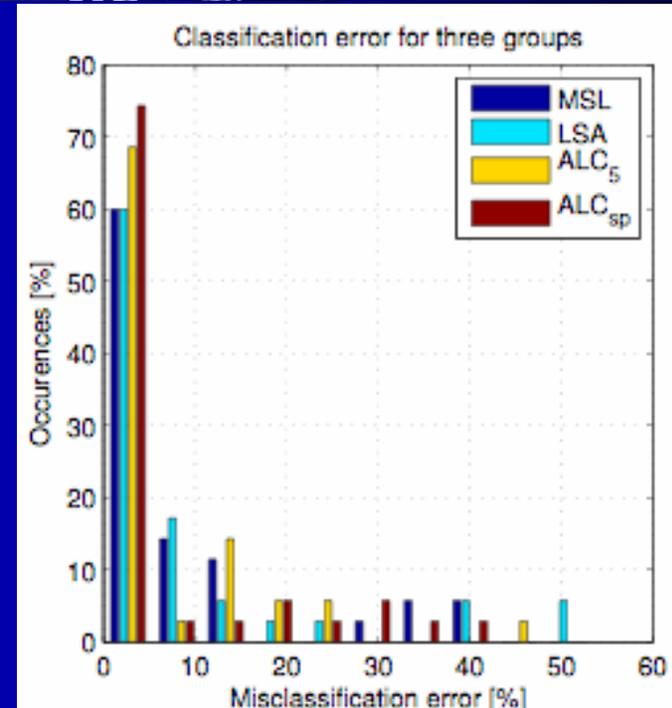
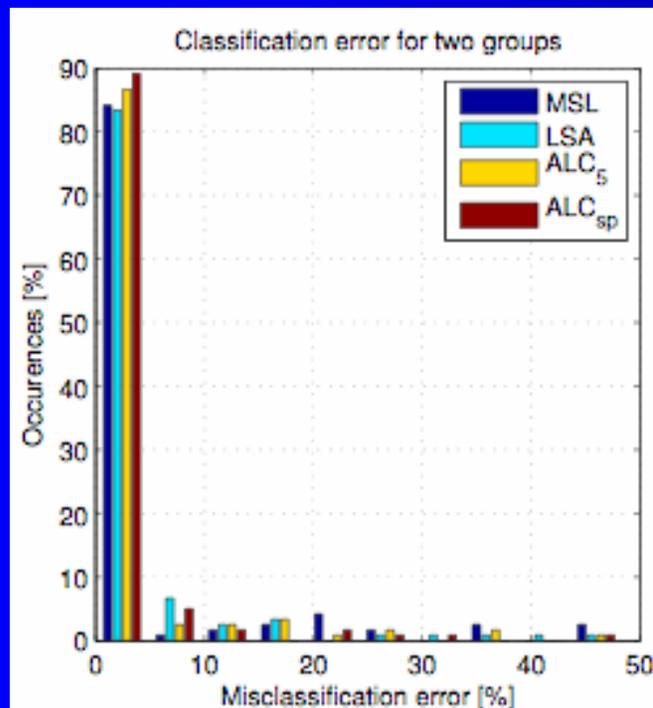
GCE: Global Consistency Error [Martin 2001]

BDE: Boundary Displacement Error [Freixenet 2002]

# Other Applications: Multiple Motion Segmentation (on Hopkins155)

QuickTime™ and a Cinepak decompressor are needed to see this picture.

QuickTime™ and a Cinepak decompressor are needed to see this picture.



Two Motions: MSL 4.14%, LSA 3.45%, ALC 2.40%, and work with up to 25% outliers.

Three Motions: MSL 8.32%, LSA 9.73%, ALC 6.26%.

## Other Applications – Clustering of Microarray Data

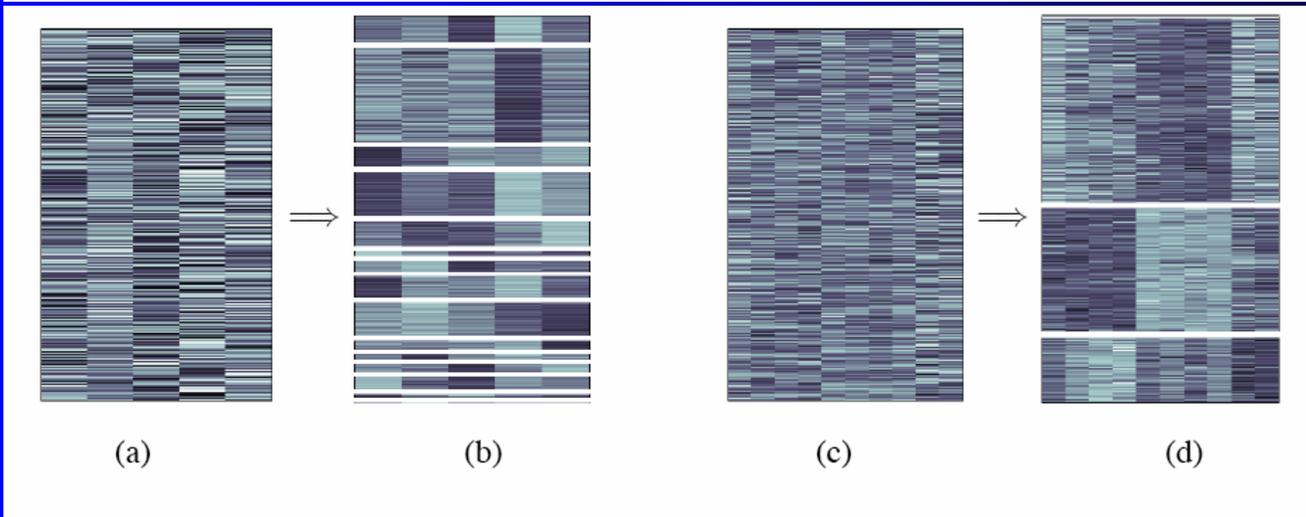
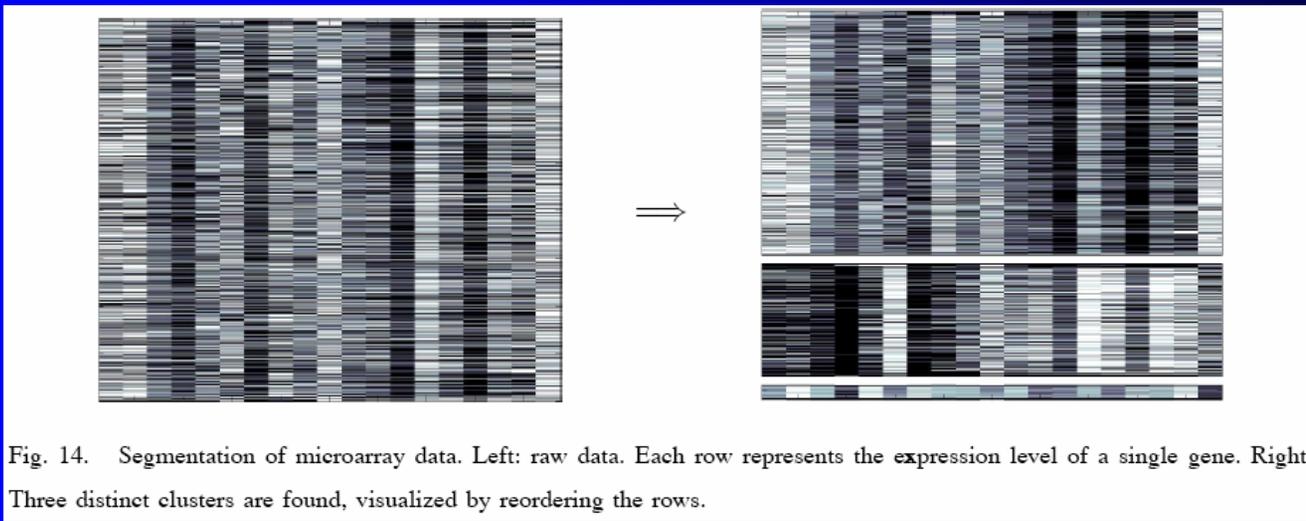
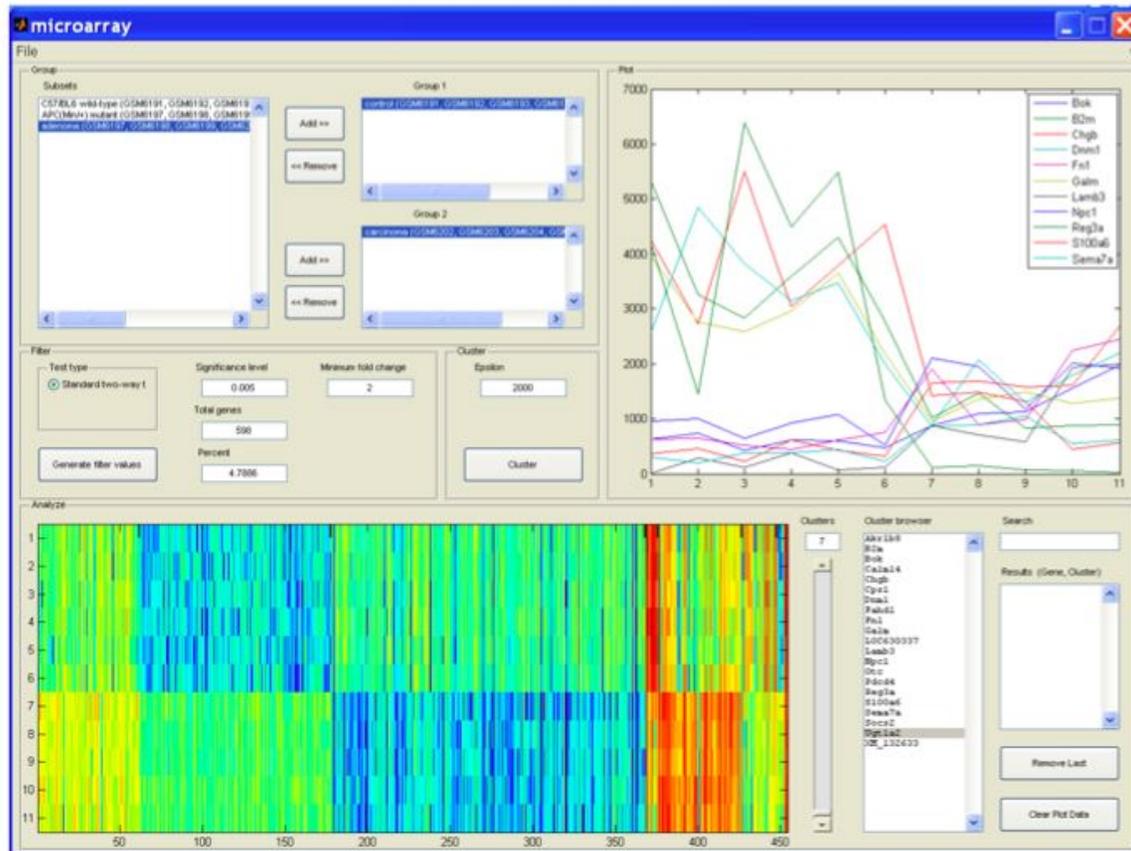


Fig. 15. Results on two microarray datasets. (a) raw yeast data. (b) segmentation, visualized by reordering rows. The greedy algorithm discovers a number of distinct clusters of varying size. (c) raw leukemia data. (d) segmentation. Three clusters are found.

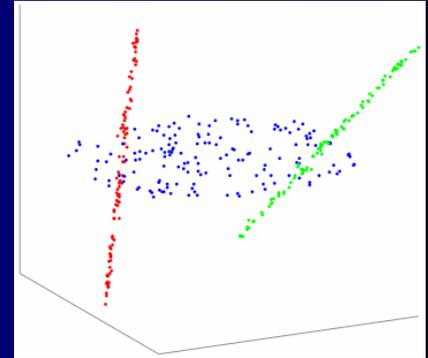
# Other Applications – Clustering of Microarray Data



## Other Applications – Supervised Classification

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**Premises:** Data  $\{y\}$  lie on an arrangement of subspaces  
 $\mathcal{A} = S_1 \cup S_2 \cup \dots \cup S_n.$



**Unsupervised Clustering**  
– Generalized PCA

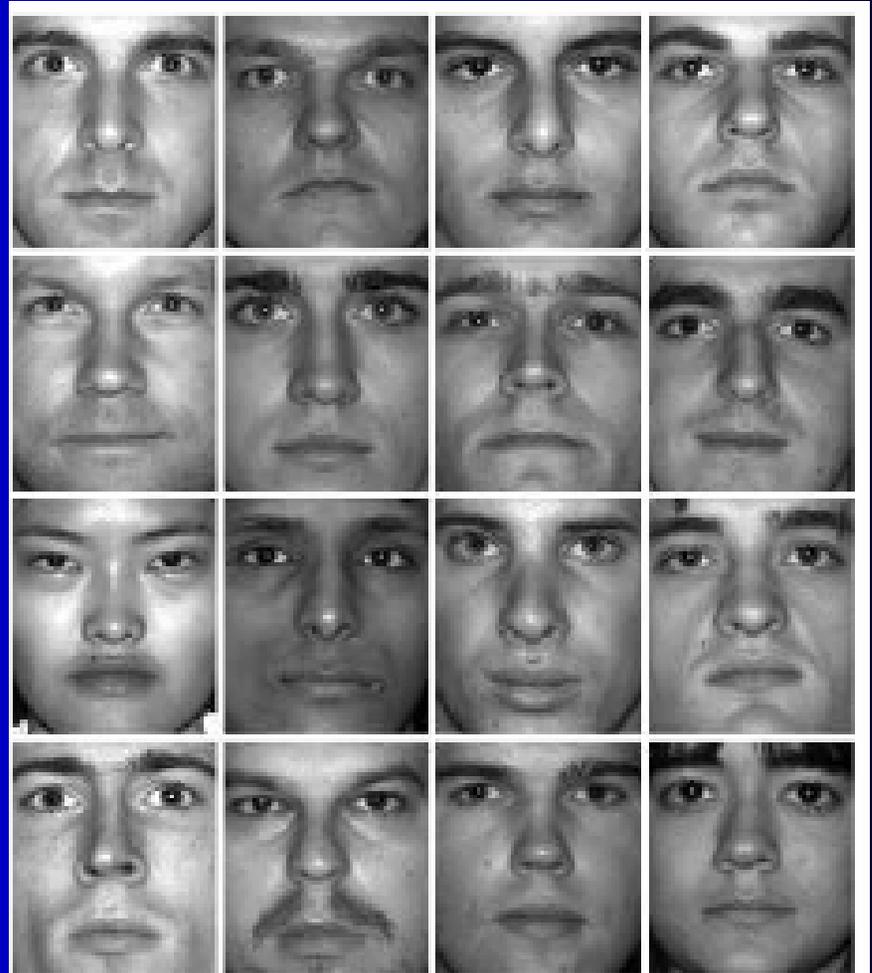
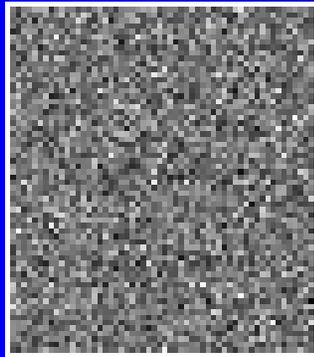
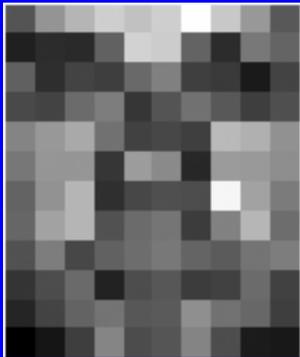
$$y = A_i \vec{\beta}_i, \quad i = 1, \dots, n.$$

**Supervised Classification**  
– Sparse Representation

$$y = [A_1, \dots, A_n]x.$$

## Other Applications – Robust Face Recognition

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## Other Applications: Robust Motion Segmentation (on Hopkins155)

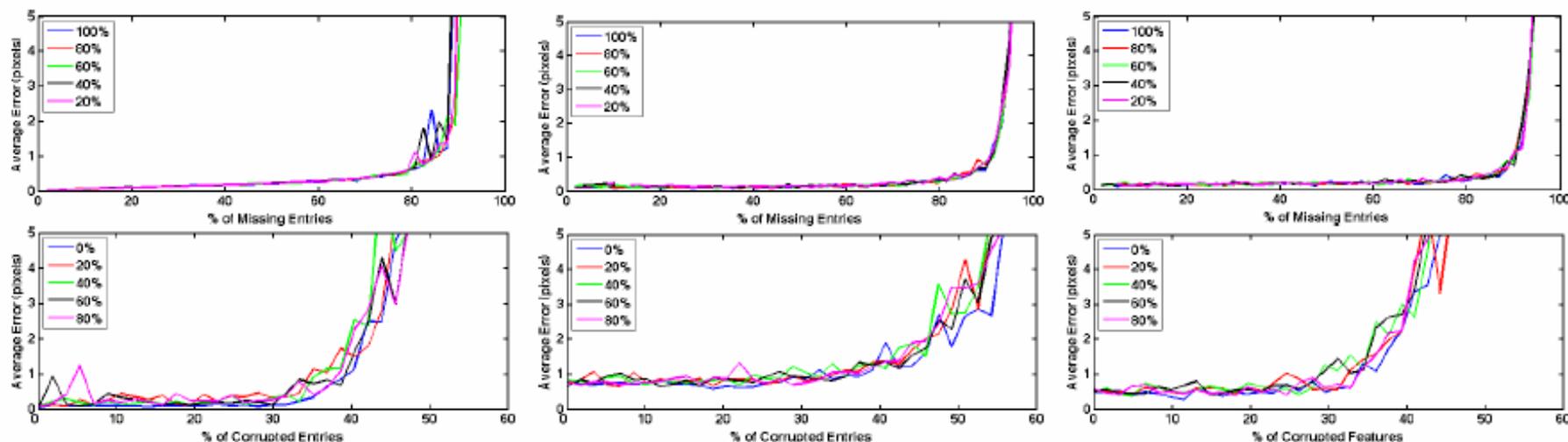
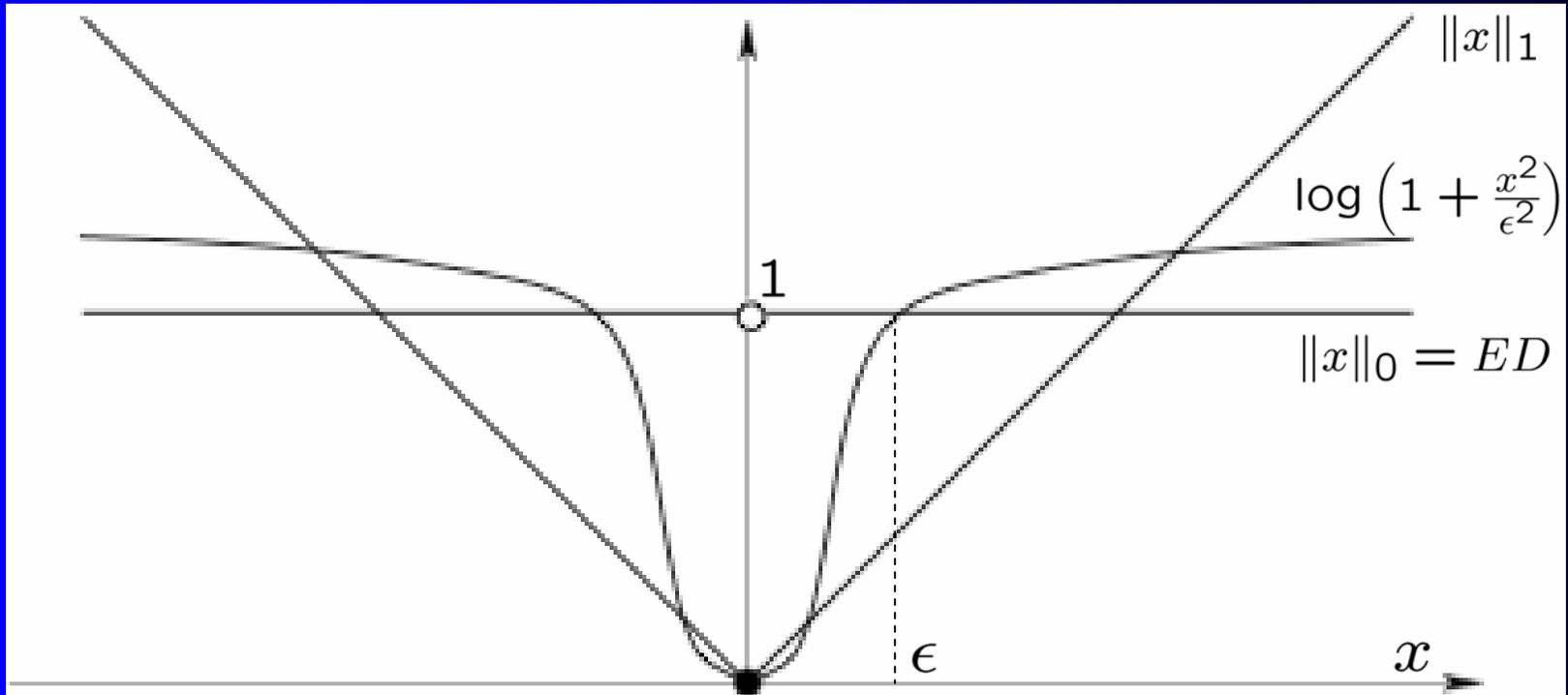


Figure 2. Errors of recovered trajectories for the sequences: “1R2RC” (left), “arm” (center), and “cars10” (right). Top: Results for our  $\ell^1$ -based trajectory completion. The different colored plots are for experiments with varying percentage of the dataset used for completion. Bottom: Results for our  $\ell^1$ -based detection and repair of corrupted trajectories. The different colors represent experiments with varying percentage of corrupted trajectories in the dataset.

**Dealing with incomplete or mistracked features with dataset 80% corrupted!**

Shankar Rao, Roberto Tron, Rene Vidal, and Yi Ma, to appear in CVPR'08

## Three Measures of Sparsity: Bits, L<sub>0</sub> and L<sub>1</sub>-Norm



**Reason:** High-dimensional data, like images, do have compact, compressible, sparse structures, in terms of their geometry, statistics, and semantics.

## Conclusions

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- Most imagery data are high-dimensional, statistically or geometrically heterogeneous, and have multi-scale structures.
  - Imagery data require hybrid models that can adaptively represent different subsets of the data with different (sparse) linear models.
  - Mathematically, it is possible to estimate and segment hybrid (linear) models non-iteratively. GPCA offers one such method.
  - Hybrid models lead to new paradigms, new principles, and new applications for image representation, compression, and segmentation.
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## Future Directions

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- Mathematical Theory
    - Subspace arrangements (algebraic properties).
    - Extension of GPCA to more complex algebraic varieties (e.g., hybrid multilinear, high-order tensors).
    - Representation & approximation of vector-valued functions.
  - Computation & Algorithm Development
    - Efficiency, noise sensitivity, outlier elimination.
    - Other ways to combine with wavelets and curvelets.
  - Applications to Other Data
    - Medical imaging (ultra-sonic, MRI, diffusion tensor...)
    - Satellite hyper-spectral imaging.
    - Audio, video, faces, and digits.
    - Sensor networks (location, temperature, pressure, RFID...)
    - Bioinformatics (gene expression data...)
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# Generalized Principal Component Analysis: Modeling and Segmentation of Multivariate Mixed Data

Rene Vidal, Yi Ma, and Shankar Sastry  
Springer-Verlag, to appear

# Thank You!