# Mathematics of Deep Learning

JHU Vision lab

#### CVPR Tutorial, Las Vegas, USA, June 26th 2016

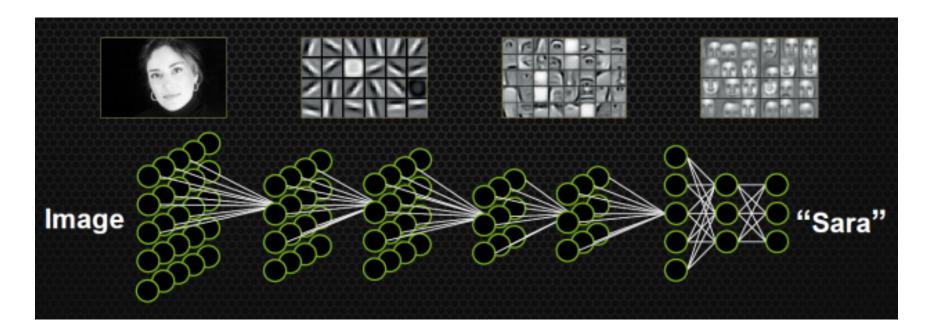
Joan Bruna (UC Berkeley), Raja Giryes (Tel Aviv University), Ben Haeffele (Hopkins), Guillermo Sapiro (Duke), Amnon Shashua (Hebrew University of Jerusalem), René Vidal (Hopkins)



## Learning Deep Image Feature Hierarchies

- Deep learning gives ~ 10% improvement on ImageNet
  - 1.2M images
  - 1000 categories
  - 60 million parameters





[1] Krizhevsky, Sutskever and Hinton. ImageNet classification with deep convolutional neural networks, NIPS'12.
 [2] Sermanet, Eigen, Zhang, Mathieu, Fergus, LeCun. Overfeat: Integrated recognition, localization and detection using convolutional networks. ICLR'14.
 [3] Donahue, Jia, Vinyals, Hoffman, Zhang, Tzeng, Darrell. Decaf: A deep convolutional activation feature for generic visual recognition. ICML'14.



# Impact of Deep Learning in Computer Vision

2012-2014 classification results in ImageNet

CNN non-CNN

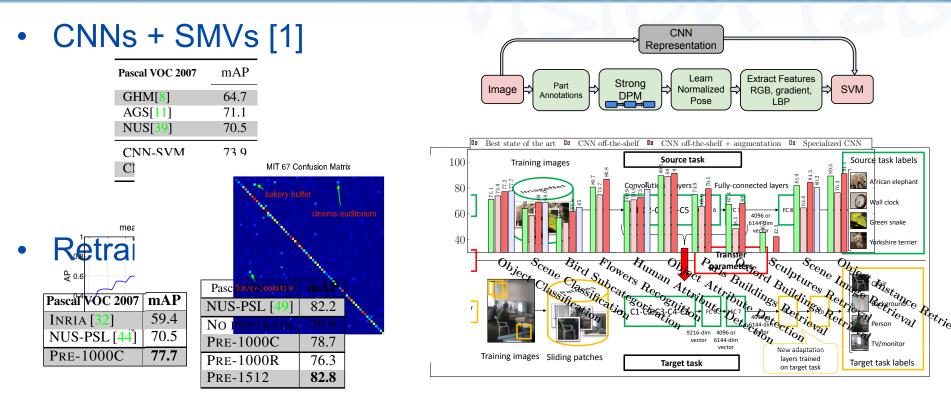
2012 Teams	%error	2013 Teams	%error	2014 Teams	%error
Supervision (Toronto)	15.3	Clarifai (NYU spinoff)	11.7	GoogLeNet	6.6
ISI (Tokyo)	26.1	NUS (singapore)	12.9	VGG (Oxford)	7.3
VGG (Oxford)	26.9	Zeiler-Fergus (NYU)	13.5	MSRA	8.0
XRCE/INRIA	27.0	A. Howard	13.5	A. Howard	8.1
UvA (Amsterdam)	29.6	OverFeat (NYU)	14.1	DeeperVision	9.5
INRIA/LEAR	33.4	UvA (Amsterdam)	14.2	NUS-BST	9.7
		Adobe	15.2	TTIC-ECP	10.2
		VGG (Oxford)	15.2	xyz	11.2
		VGG (Oxford)	23.0	UvA	12.1

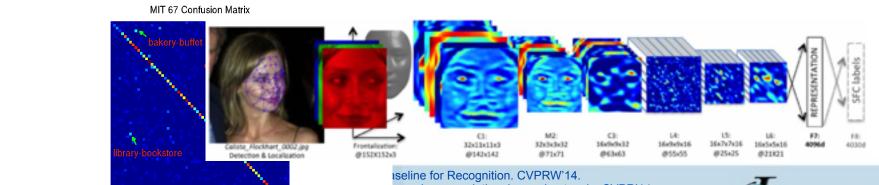
2015 results: MSR under 3.5% error using 150 layers!



Slide from Yann LeCun's CVPR'15 plenary and ICCV'15 tutorial intro by Joan Bruna

## Transfer from ImageNet to Other Datasets





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0.8

0.6

0.4

aseline for Recognition. CVPRW'14. ns using convolutional neural networks CVPR'14 ance in Face Verification. CVPR'14

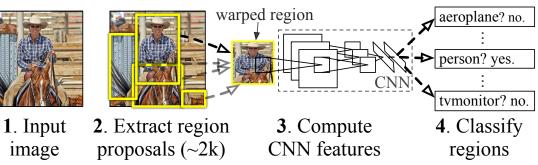


## Transfer from Classification to Other Tasks

#### • CNNs + SVMs for object detection [1,2]

mAP	
33.4	
35.1	
39.7	
40.4	
50.2	
53.7	

**R-CNN:** Regions with CNN features



#### CNNs for pose estimation [3] and semantic segmentation [4]



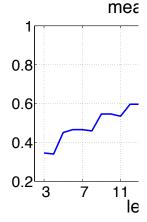
[1] Girshick, Donahue, Darrell and Malik. Rich feature hierarchies for accurate object detection and semantic segmentation, CVPR'14
 [2] Sermanet, Eigen, Zhang, Mathieu, Fergus, LeCun. OverFeat: Integrated Recognition, Localization and Detection using Convolutional Networks. ICLR
 [3] Tompson, Goroshin, Jain, LeCun, Bregler. Efficient Object Localization Using Convolutional Networks. CVPR'15
 [4] Pinheiro, Collobert, Dollar. Learning to Segment Object Candidates. NIPS'15

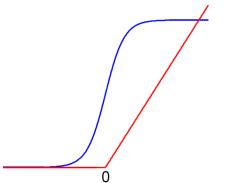


# Why These Improvements in Performa

- Features are learned rather than hand-crafted
- More layers capture more invariances [1]
- More data to train deeper networks
- More computing (GPUs)
- Better regularization: Dropout
- New nonlinearities
  - Max pooling, Rectified linear units (ReLU)
- Theoretical understanding of deep networks remains shallow

[1] Razavian, Azizpour, Sullivan, Carlsson, CNN Features off-the-shelf: an Astounding Baseline for Recognition. CVPRW'14.







### Early Theoretical Results on Deep Learning

#### Approximation theory

 Perceptrons and multilayer feedforward networks are universal approximators: Cybenko '89, Hornik '89, Hornik '91, Barron '93

#### Optimization theory

- No spurious local optima for linear networks: Baldi & Hornik '89
- Stuck in local minima: Brady '89
- Stuck in local minima, but convergence guarantees for linearly separable data: Gori & Tesi '92
- Manifold of spurious local optima: Frasconi '97

[1] Cybenko. Approximations by superpositions of sigmoidal functions, Mathematics of Control, Signals, and Systems, 2 (4), 303-314, 1989.

- [2] Hornik, Stinchcombe and White. Multilayer feedforward networks are universal approximators, Neural Networks, 2(3), 359-366, 1989.
- [3] Hornik. Approximation Capabilities of Multilayer Feedforward Networks, Neural Networks, 4(2), 251–257, 1991.

[4] Barron. Universal approximation bounds for superpositions of a sigmoidal function. IEEE Transactions on Information Theory, 39(3):930–945, 1993.

[5] P Baldi, K Hornik, Neural networks and principal component analysis: Learning from examples without local minima, Neural networks, 1989.
[6] Brady, Raghavan, Slawny. Back propagation fails to separate where perceptrons succeed. IEEE Trans Circuits & Systems, 36(5):665–674, 1989.
[7] Gori, Tesi. On the problem of local minima in backpropagation. IEEE Trans. on Pattern Analysis and Machine Intelligence, 14(1):76–86, 1992.
[8] Frasconi, Gori, Tesi. Successes and failures of backpropagation: A theoretical. Progress in Neural Networks: Architecture, 5:205, 1997.



### **Recent Theoretical Results on Deep Learning**

#### • Invariance, stability, and learning theory

- Scattering networks: Bruna '11, Bruna '13, Mallat '13
- Deformation stability for Lipschitz non-linearities: Wiatowski '15
- Distance and margin-preserving embeddings: Giryes '15, Sokolik '16
- Geometry, generalization bounds and depth efficiency: Montufar '15, Neyshabur '15, Shashua '14 '15 '16

#### Optimization theory and algorithms

- Learning low-degree polynomials from random initialization: Andoni'14
- Characterizing loss surface and attacking the saddle point problem: Dauphin '14, Choromanska '15, Chaudhuri '15
- Global optimality in neural network training: Haeffele '15
- Training NNs using tensor methods: Janzamin '15
- [1] Bruna-Mallat. Classification with scattering operators, CVPR'11. Invariant scattering convolution networks, arXiv'12. Mallat-Waldspurger. Deep Learning by Scattering, arXiv'13. [2] Wiatowski, Bölcskei. A mathematical theory of deep convolutional neural networks for feature extraction. arXiv 2015.
- [3] Giryes, Sapiro, A Bronstein. Deep Neural Networks with Random Gaussian Weights: A Universal Classification Strategy? arXiv:1504.08291.

[4] Sokolic. Margin Preservation of Deep Neural Networks, 2015

- [5] Montufar. Geometric and Combinatorial Perspectives on Deep Neural Networks, 2015.
- [6] Neyshabur. The Geometry of Optimization and Generalization in Neural Networks: A Path-based Approach, 2015.
- [7] Andoni, Panigraphy, Valiant, Zhang. Learning Polynomials with Neural Networks. ICML 2014.

[8] Dauphin, Pascanu, Gulcehre, Cho, Ganguli, Bengio, Identifying and attacking the saddle point problem in high-dimensional non-convex optimization. NIPS 2014

- [9] Choromanska, Henaff, Mathieu, Arous, LeCun, "The Loss Surfaces of Multilayer Networks," AISTAT 2015.
- [10] Chaudhuri and Soatto The Effect of Gradient Noise on the Energy Landscape of Deep Networks, arXiV 2015.
- [11] Haeffele, Vidal. Global Optimality in Tensor Factorization, Deep Learning and Beyond, arXiv, 2015.
- [12] Janzamin, Sedghi, Anandkumar, Beating the Perils of Non-Convexity: Guaranteed Training of Neural Networks using Tensor Methods, arxiv 2015.

### Motivations and Goals of this Tutorial

- **Motivation:** Deep networks have led to dramatic improvements in performance for many tasks, but the mathematical reasons for this success remain unclear.
- **Goal:** Review very recent work that aims at understanding the mathematical reasons for the success of deep networks.
- What we will do: Study theoretical questions such as
  - What properties of images are being captured/exploited by DNNs?
  - Can we ensure that the learned representations are globally optimal?
  - Can we ensure that the learned representations are stable?
- What we will not do: Show X% improvement in performance for a particular application.



### **Tutorial Schedule**

- 14:00-14:15: René Vidal Introduction
- 14:15-15:00: Amnon Shashua On Depth Efficiency of Convolutional Networks: Theory and Implications for Practical Architectures
- 15:00-15:45: René Vidal and Benjamin Haeffele Global Optimality and Regularization in Deep Learning
- 15:45-16:15: Coffee Break
- 16:15-17:00: Raja Giryes and Guillermo Shapiro Data Structure Based Theory of Deep Learning
- 17:00-17:45: Joan Bruna Addressing Curse of Dimensionality with Convolutional Neural Networks
- 17:45-18:00: Discussion

